



Brief communication: Accuracy of the fallen blocks volume-frequency law

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Abstract. De Biagi et al. (2017) have proposed a procedure for building a fallen block volume-frequency law for rockfall phenomenon. The input data are from both the recording of rockfall events and from the survey of fallen block volumes. The epistemic and aleatoric uncertainties present in the approach affect the value of the parameters of the law. It is shown how to quantify the errors due to missed events, to an observation period of finite duration and to a limited set of measured blocks. At the end, the procedure outputs corrective parameters to compute a design volume for rockfall analysis and engineering calculations.

1 Introduction

In a recent paper, De Biagi et al. (2017) proposed a novel approach for defining a block volume-frequency law to be used in rockfall hazard quantification and in the design of rockfall protection structures. Given a representative area where the rockfall phenomenon occurs, the method considers the temporal occurrences of the falling block events separately from the deposit volumes distribution. The input data for implementing the procedure are taken from observations and measurements. The present paper deals with the effects of epistemic uncertainties on the value of volumes predicted through the frequency law described in De Biagi et al. (2017). As summarized by Straub and Schubert (2008), the epistemic uncertainties are related to our incomplete knowledge of the process, often because of limited data. Referring to the aforementioned law, the uncertainty derives from a limited number of recorded events and surveyed blocks. In the following, the main steps required for deriving the block volume-frequency law are proposed.

1. Surveying: a catalogue of rockfall events, \mathcal{C}° , is drawn up, i.e. a catalogue containing the size of the falling blocks, the corresponding temporal information (date) and a list of fallen block measured volumes, \mathcal{F}° , that may have fallen down at any time. Both \mathcal{C}° and \mathcal{F}° must relate to the same representative area, i.e. the portion of deposit beyond a defined line, say the foot of the slope, where the hazard is computed.
2. Threshold volume and reduced data sets: the catalogue of the events \mathcal{C}° contains all the recorded events gathered in a time window of temporal length, t° . Since there is the possibility that small events have not always been recorded, a threshold volume V_t is established, defined as the minimum size of a fallen block that has always been observed and recorded (after its occurrence). Entries related to volumes smaller than V_t are removed from \mathcal{C}° and \mathcal{F}° . These new data sets are denoted by reduced catalogue, \mathcal{C} , and reduced list, \mathcal{F} , and have a number of entries equal to n and N , respectively. The temporal length t° is increased to consider that the observations began with the occurrence of an event, i.e. $t = t^\circ + \frac{t^\circ}{2n}$.
3. Choosing the probabilistic models: two probabilistic models are chosen. One should be able to describe the temporal occurrences of the events of the reduced catalogue, the other the distribution of the surveyed volumes. Under the hypothesis of the Poisson point process, a Poisson distribution, characterized by the parameter $\lambda > 0$, is considered for the occurrence of falling block events. A Pareto distribution is adopted for the latter, as stated by the power laws found in the literature. In De Biagi et al. (2017), a generalized Pareto distri-

bution (GPD), which can be ascribed to a Pareto type II distribution, is adopted for describing the distribution of the surveyed volumes. The two probabilistic models are merged together. That is, the following equality holds:

$$\frac{1}{\lambda T} = \bar{F}(v), \tag{1}$$

where T is the return period, v is a given volume, and \bar{F} is the survival function of the Pareto distribution. The survival function is the complementary cumulative distribution function: $\bar{F}_V(v) = 1 - F_V(v)$.

4. Evaluation of the parameters of the distribution: the estimate of the parameters can be obtained through maximum likelihood methods from the reduced data sets. Referring to the occurrences process, the ratio $\hat{\lambda} = n/t$, i.e. the annual frequency of events larger than V_t , is an unbiased estimate of Poisson's occurrence parameter. Referring to the distribution of the volumes, details are provided in Sect. 2.

2 Pareto type I distribution

To deal with a reduced number of parameters, a Pareto type I (Pareto I) distribution is adopted for describing the distribution of the surveyed volumes listed in \mathcal{F} . The survival function of Pareto I is

$$\bar{F}(v) = \begin{cases} 1 & v < \mu \\ \left(\frac{v}{\mu}\right)^{-\alpha} & v \geq \mu \end{cases}, \tag{2}$$

where μ is the location parameter and α is the shape parameter, and both are positive.

As reported in the literature (see e.g. Arnold, 2015 and the references cited herein), various procedures for estimating the parameters of Pareto I are proposed. In the present analysis, the threshold volume is the estimate of the location parameter, i.e. $\hat{\mu} = V_t$. This value is arbitrary and strictly depends on the possibility of observing small falling block events. Referring to the shape parameter, in Arnold (2015), the following estimator is proposed:

$$\hat{\alpha} = N \left[\sum_{i=1}^N \ln \left(\frac{v_i}{V_t} \right) \right]^{-1}, \tag{3}$$

where v_i is the volume of each block measured in the representative area. Hence, the survival function becomes

$$\bar{F}(v) = \begin{cases} 1 & v < V_t \\ \left(\frac{v}{V_t}\right)^{-\hat{\alpha}} & v \geq V_t \end{cases}. \tag{4}$$

Substituting Eq. (1) with Eq. (4), the volume $v(T)$ corresponding to a given return period (larger than $1/\hat{\lambda}$) is determined:

$$v(T) = V_t \left(\hat{\lambda} T \right)^{\frac{1}{\hat{\alpha}}}. \tag{5}$$

3 Reliability of the block volume-frequency law

One of the key questions that arose in the discussion of ‘‘Estimation of the return period of rockfall blocks according to their size’’ relates both to the minimum number of observed events and to the minimum number of surveyed blocks needed to build the curve. In the present section, the reliability of the results obtained through Eq. (5) is discussed in the light of the consistency of the catalogue of the events \mathcal{C} and of the list of measured blocks \mathcal{F} . In the following, the volume of the block with a return period T determined through Eq. (5), with Pareto parameter vector $\boldsymbol{\pi}$, after the observation of n events during t time, is denoted by $\mathcal{V}(T, t, n, \boldsymbol{\pi})$.

3.1 Error due missed recorded events

The temporal information is relevant for establishing a link between the return period and block volume. In the present section, the effects of missed events are analysed. Supposing that p events larger than V_t ($p \in \mathbb{N}$) have not been observed even if they have occurred, they would be part of the reduced catalogue \mathcal{C} . Since the length of the observation period does not change, the value of the estimate of λ varies: the corrected value, λ_c , is

$$\lambda_c = \frac{(2n + 1)(n + p)^2}{n^2(2n + 2p + 1)} \hat{\lambda}, \tag{6}$$

resulting in $\lambda_c > \hat{\lambda}$. Using the notation previously illustrated, this implies $\mathcal{V}(T, t, n + p, \boldsymbol{\pi}) > \mathcal{V}(T, t, n, \boldsymbol{\pi})$. In other words, if it is supposed that events have not been observed even if they have occurred, the volume at a given return period is underestimated.

The error due to the lack of p observed events is computed in terms of ratio between the value of the volumes corresponding to the same return period, T , i.e.

$$\mathcal{E}_{T,p} = \frac{\mathcal{V}(T, t, n + p, \boldsymbol{\pi})}{\mathcal{V}(T, t, n, \boldsymbol{\pi})}. \tag{7}$$

Substituting the known terms, the ratio of Eq. (7) can be rewritten as

$$\mathcal{E}_{T,p} = \left[\frac{(2n + 1)(n + p)^2}{n^2(2n + 2p + 1)} \right]^{\frac{1}{\hat{\alpha}}} = \mathcal{E}_p. \tag{8}$$

It can be noted that, as expected, $\mathcal{E}_{T,p}$ is greater than one; in addition, $\mathcal{E}_{T,p}$ does not depend on the return period of the estimated volume; thus it can be simply named \mathcal{E}_p . The length

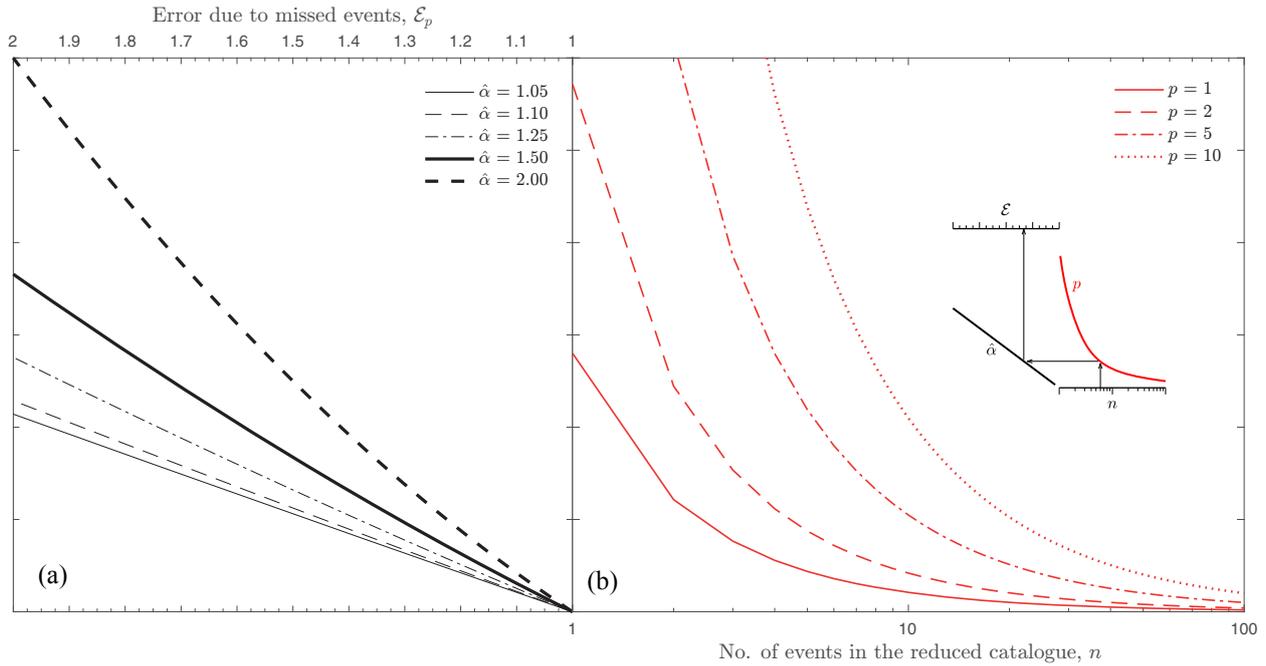


Figure 1. Design graph for the estimation of the error due to missed events \mathcal{E}_p , as a function of the number of events n in the reduced catalogue \mathcal{C} , the expected number of missed events p , and Pareto type I distribution shape parameter $\hat{\alpha}$.

of the observation period is not entered in Eq. (8). For practical use, a design chart, which can be used in various ways depending on the required data, is proposed in Fig. 1.

As reported in the sketch of the plot, if the expected number of missed events p and the shape parameter $\hat{\alpha}$ of Pareto I are known, the error \mathcal{E}_p is derived from the number of events in the reduced catalogue, n . Vice versa, given a value of the error, the consistency of the reduced catalogue, i.e. the number of events, can be determined.

3.2 Error due to the stochastic nature of the occurrence process

The events of the reduced catalogue \mathcal{C} within the temporal range t are considered to be a realization of a Poisson point process. The error due to the aleatoric nature of the process is detailed in this section. $P_{n,t}(\pi)$ denotes the probability that, given an average annual frequency equal to π , n events are observed during the period t , i.e.

$$P_{n,t}(\pi) = \frac{(\pi t)^n}{n!} e^{-\pi t}. \tag{9}$$

In De Biagi et al. (2017), the temporal parameter is $\hat{\lambda} = n/t$, the value at which the Eq. (9) is maximized. However, $\hat{\lambda}$ is an estimate of the parameter, which does not necessarily coincide with the true value. Figure 2a plots the value of $P_{n,t}$ against π for different catalogues with $\hat{\lambda} = 0.2$.

The area underlined by each curve is equal to t^{-1} . Figure 2b plots the normalized curves $Q_{n,t}(\pi) = t P_{n,t}(\pi)$, i.e. the curves with a unitary underlying area.

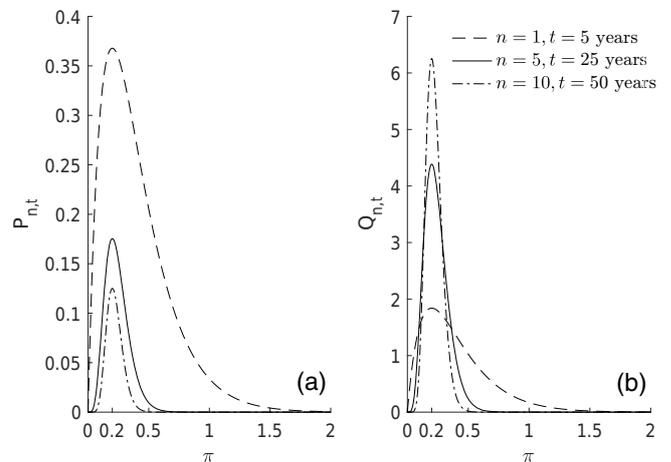


Figure 2. (a) Plot of $P_{n,t}$ against π , (b) plot of the normalized function, $Q_{n,t}$ against π . The legend relates to both axes.

For design purposes, given n and t , the value λ_i , corresponding to a given i percentile of the curve $Q_{n,t}(\pi)$ can be used instead of $\hat{\lambda}$. For example, considering the 90 percentile, the value of λ_{90} to be considered is the one for which the following equalities chain subsists

$$\int_0^{\lambda_{90}} Q_{n,t}(\pi) d\pi = 1 - \frac{\Gamma(n+1, \lambda_{90}t)}{\Gamma(n+1)} = 0.90, \tag{10}$$

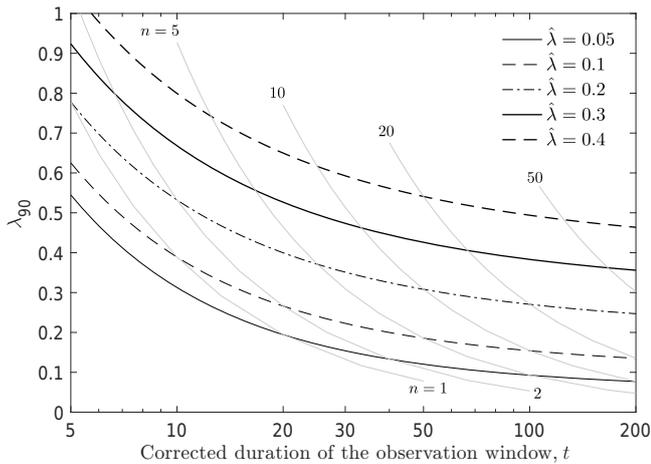


Figure 3. The value of λ_{90} as a function of the duration of the observation window, t , or the number of events, n , and the estimated Poisson occurrence parameter $\hat{\lambda}$.

where $\Gamma(\bullet)$ is the Gamma function and $\Gamma(\bullet, \circ)$ is the upper incomplete Gamma function. In other words, if n events are observed during the period t , there is 90% probability that the true annual frequency parameter is lower than λ_{90} . Figure 3 plots the value of λ_{90} as a function of the duration of the observation window and the estimated $\hat{\lambda}$. It is seen that λ_{90} tends to $\hat{\lambda}$ as much as the duration of the observation window increases.

Accounting for the effects of the variability of the estimate of the frequency parameter has direct consequences on the value of the computed volume, Eq. (5). The effects on the generated volume can be computed in terms of ratio \mathcal{D}_{90} between the volume obtained with λ_{90} and the reference (i.e. with $\hat{\lambda}$):

$$\mathcal{D}_{90} = \frac{V_t(\lambda_{90}T)^{\frac{1}{\alpha}}}{V_t(\hat{\lambda}T)^{\frac{1}{\alpha}}} = \left(\frac{\lambda_{90}}{\hat{\lambda}}\right)^{\frac{1}{\alpha}}. \tag{11}$$

3.3 Error due to a reduced number of measured blocks

In this section, the error related to the consistency of the list of block volumes surveyed in the representative area is determined and discussed. As already discussed in De Biagi et al. (2017), the choice of V_t depends on the precision of the historical records performed in the representative area. On the contrary, the value of the estimate of the shape parameter, $\hat{\alpha}$, depends on the consistency of the reduced list \mathcal{F} .

As proved by Malik (1970), the estimate $\hat{\alpha}$ follows a Gamma distribution, or equivalently, $2\alpha N/\hat{\alpha} \sim \chi^2_{2N-2}$, where α represents the real value of the Pareto I shape parameter, while $\hat{\alpha}$ is its estimate. Asymptotic normality is proved, since the inverse of a chi-squared distribution is very close to a normal distribution.

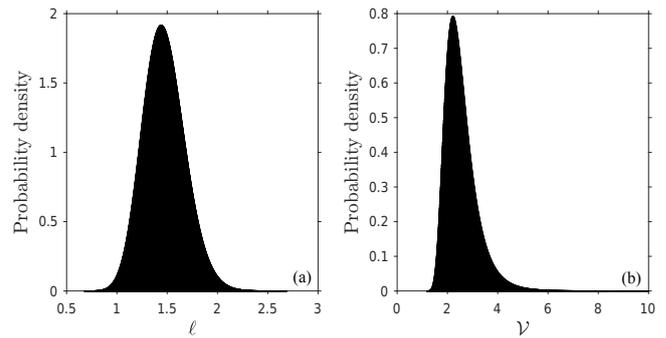


Figure 4. Empirical distribution of ℓ and the corresponding \mathcal{U} . The example refers to $\hat{\alpha} = 1.50$, $N = 50$, $\lambda T = 10$.

Considering the estimate of the shape parameter as a variate $\ell \sim \chi^2_{2N-2} \frac{\hat{\alpha}}{2N}$, fixing the values of n , t and T , a distribution of volumes is expected. For example, given $\hat{\alpha} = 1.50$, $N = 50$, $\hat{\lambda}T = 10$ and $V_t = 0.5$, the volume computed through Eq. (5) is 2.32 m^3 . A sample of 1×10^6 values of ℓ were generated through a Monte Carlo technique: left-hand side plot of Fig. 4 shows the probability density of ℓ and the right-hand side axes plot the probability density of the volumes computed using the generated ℓ .

The ratio between the 90 percentile volume (3.36 m^3) and the reference value (2.32 m^3) is denoted by $\mathcal{U}_{90} = 3.36/2.32 = 1.45$.

The error due to the consistency of the reduced list \mathcal{F} is evaluated in term of ratio \mathcal{U} between the generated volumes (e.g. with the ℓ) and the reference value determined using the estimate $\hat{\alpha}$. In detail,

$$\mathcal{U} = \frac{\mathcal{V}(T, t, n, \pi^*)}{\mathcal{V}(T, t, n, \hat{\pi})} = \frac{V_t(\lambda T)^{\frac{1}{\alpha}}}{V_t(\lambda T)^{\frac{1}{\hat{\alpha}}}}, \tag{12}$$

where π^* is the parameter vector containing the generated ℓ , while $\hat{\alpha}$ is included in $\hat{\pi}$. The previous reduces to

$$\mathcal{U} = (\lambda T)^{\frac{1}{\alpha} - \frac{1}{\hat{\alpha}}}. \tag{13}$$

The value of \mathcal{U} related, say, to 90 percentile can be relevant for design purposes. Because of the reciprocity of the terms composing the exponent of Eq. (13), this corresponds to 10 percentile of the distribution of ℓ , i.e.

$$\mathcal{U}_{90} = (\lambda T)^{\frac{1}{\hat{\alpha}} - \frac{1}{\alpha}}, \tag{14}$$

where

$$\ell_{10} = \chi^2_{2N-2, 0.1} \frac{\hat{\alpha}}{2N}. \tag{15}$$

As for the previous case, for practical use, a design chart is proposed in Fig. 5. As reported in the sketch of the plot, once the estimate $\hat{\alpha}$ is computed given N measured blocks, the error corresponding to 90 percentile can be determined for different $\hat{\lambda}T$ values.

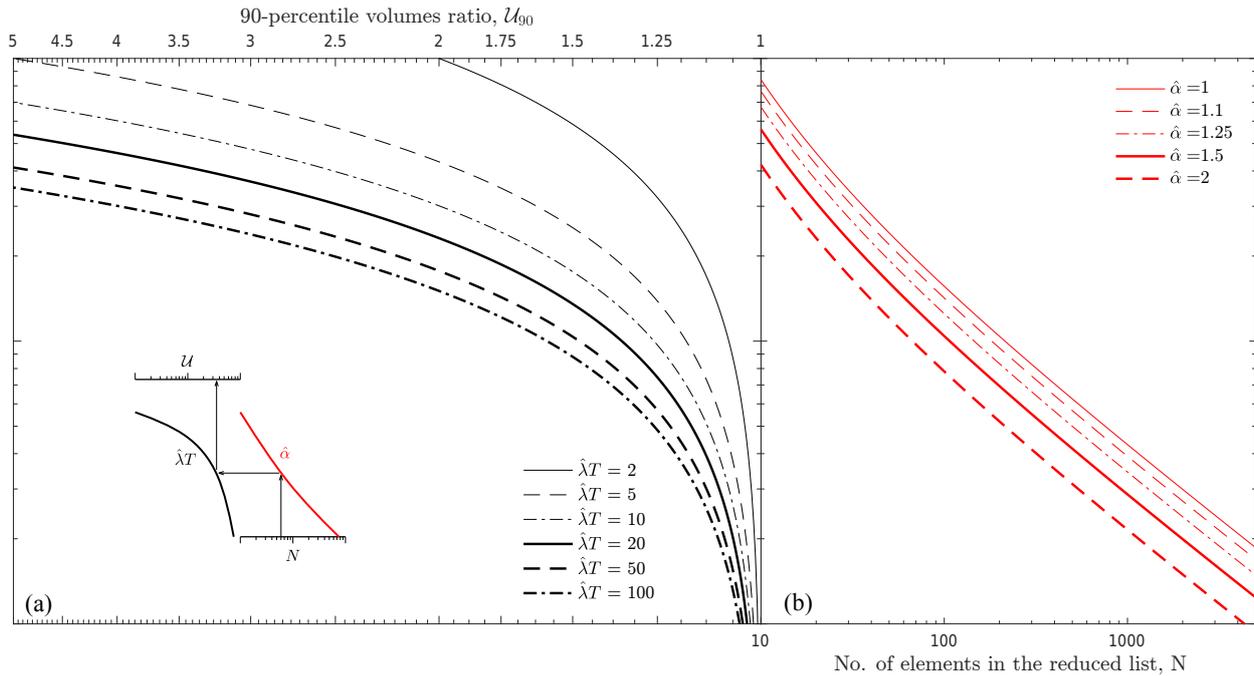


Figure 5. Design graph for the estimation of the volume multiplier (90 percentile) accounting for the number N of measured blocks in the reduced list, \mathcal{F}^* , and the term $\hat{\lambda}T$, and Pareto type I distribution shape parameter, $\hat{\alpha}$.

4 Conclusions

The quality of the survey and the precision in recording rock-fall events occurring in a study area play a relevant role in computing the volumes that would probably fall by a certain period. This information is of primary importance for the design of protection devices, for the implementation of reliability differentiation in structural engineering and for computing the risk in a certain area. From Fig. 1 it emerges that, given a number of missed events p , the error \mathcal{E}_p increases as much as the estimate of Pareto I shape parameter α reduces. In general, supposing that 20% of the events have not been recorded, 10 events are sufficient to keep $\mathcal{E}_{20\%} < 1.20$. Referring to the amount of measured volumes for estimating α , the value largely depends on the return period of the expected volume, rather than to the estimate $\hat{\alpha}$. For example, when $N = 100$ and $\hat{\alpha} = 1.50$, the \mathcal{U}_{90} ranges from 1.05 to 1.70 as $\hat{\lambda}T$ varies from 2 to 100. For small return periods, the consistency of the reduced list \mathcal{F} can somehow be limited. Keeping \mathcal{U}_{90} below 1.20 for a large range of $\hat{\lambda}T$ would imply having a reduced list containing a thousand of records.

Anyway, for design purposes, for a given catalogue of events (even limited) and a list of blocks, once the required return period T is determined, the volume V_k of the 90 percentile block can be determined as follows, also taking into account the potential errors due to p missed events:

$$V_k(T) = \mathcal{E}_p \mathcal{U}_{90} \mathcal{D}_{90} \left[V_t(\hat{\lambda}T)^{\frac{1}{\hat{\alpha}}} \right]. \quad (16)$$

Table 1. Error calculations for Buisson and Becco dell’Aquila at $T = 50$ years, supposing $p = 1$.

	Buisson	Becco dell’Aquila
n	5	3
t	25.3 yr	22.17 yr
$\hat{\lambda}$	0.1976 yr ⁻¹	0.1353 yr ⁻¹
$\hat{\alpha}$	0.4101	0.9788
$v(50 \text{ yr})$	40 m ³	30 m ³
ℓ_{10}	0.4173	0.7863
λ_{90}	0.3366	0.3013
\mathcal{E}_1	1.4314	1.39
\mathcal{U}_{90}	3.7847	1.61
\mathcal{D}_{90}	3.0695	2.27
$V_k(50 \text{ yr})$	665 m ³	665 m ³

Although a complete error analysis for Pareto Type II is needed, referring to the examples of Buisson and Becco dell’Aquila of De Biagi et al. (2017), the error components are evaluated at a return period $T = 50$ years, with a number of missed events $p = 1$. From Figs. 4 and 5 of De Biagi et al. (2017), the volumes $v(50 \text{ yr})$ are approximately 40 and 30 m³, respectively. The calculations are reported in Table 1. It clearly appears that a high number of observations and surveyed blocks are fundamental for keeping the errors low.

Data availability. Refer to De Biagi et al. (2017) for the data sets used in this article.

Competing interests. The author declares that he has no conflict of interest.

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