Hydro-meteorological reconstruction and geomorphological impact assessment of the October 2018 catastrophic flash flood at Sant Llorenç, Mallorca (Spain)

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Abstract. An extraordinary convective rainfall event, unforeseen by most numerical weather prediction models, generated a devastating flash flood ($305 \text{ m}^3\text{s}^{-1}$) in the town of Sant Llorenç des Cardassar, Mallorca, on 9 October 2018. Four people died inside this village, while casualties were up to 13 over the entire affected area. This extreme event has been reconstructed by implementing an integrated flash flood modelling approach in the Ses Planes catchment up to Sant Llorenç (23.4 km²), based on three components: (i) generation of radar-derived precipitation estimates, (ii) modelling of accurate discharge hydrographs yielded by the catchment (using FEST and KLEM models), and (iii) hydraulic simulation of the event and mapping of affected areas (using HEC-RAS). Radar-derived rainfall estimates show very high agreement with rain gauge data ($R^2 = 0.98$). Modelled flooding extent is in close agreement with the observed extension by the Copernicus Emergency Management Service, based on Sentinel-1 imagery, and both far exceed the extension for a 500-year return period flood. Hydraulic simulation revealed that water reached a depth of 3 m at some points, and modelled water depths highly correlate ($R^2 = 0.91$) with in situ after-event measurements. The 9 October flash flood eroded and transported woody and abundant sediment debris, changing channel geomorphology. Water velocity greatly increased at bridge locations crossing the river channel, especially at those closer to the Sant Llorenç town centre. This study highlights how the very low predictability of this type of extreme convective rainfall events and the very short hydrological response times typical of small Mediterranean catchments continue to challenge the implementation of early warning systems, which effectively reduce people’s exposure to flash flood risk in the region.

1 Introduction

The European Union member states reported 3198 floods occurred between 1980 and 2015 (EU Floods Directive 2007/60/EC) (http://rod.eionet.europa.eu/obligations/601, last access: 26 June 2019; https://www.eea.europa.eu/data-and-maps/data/european-past-floods, last access: 24 June 2019). These floods were responsible for 4806 fatalities and an approximate total damage cost of EUR 115 113 million. Spain reported more than 20 floods per 10 000 km², one of the highest in Europe, with 652 fatalities (European Environment Agency, 2016). In 2018, flash floods killed 152 people across Europe, parts of northern Africa and the Middle East. The deadliest flash floods occurred in the Mediterranean area (Mallorca, Tunisia, Veneto, Sicily and Jordan), including five events with 70 fatalities, concentrated in almost 1 month: 9, 17 and 29 October as well as 3 and 9 November (European Severe Weather Database; https://www.eswd.eu/, last access: 26 June 2019).

Flash floods are known as high-intensity precipitation episodes with a convective origin that fall over small catchment headwaters, generating a fast hydrological response characterized by a sudden flow event with steep rising and falling limbs and short lag times (i.e. Marchi et al., 2010;
Borga et al., 2014). In the western Mediterranean region, flash floods occur mostly in the autumn (Llasat et al., 2010), and generally they are more intense than in continental areas (Gaume et al., 2009). The relatively high sea surface temperature increases the convective available potential energy of the overlying moist air masses through sensible and latent heat flux exchanges. Together with the intrusion of cold air aloft and the presence of mesoscale vertical forcing mechanisms, the complex orography and acute land–sea contrasts promote the lifting of low-level unstable air, favouring the triggering of deep moist convection (Romero et al., 1998; Martínez et al., 2008; Cohuet et al., 2011). Despite some important flash floods being produced by heavy precipitations that last less than 1 or 2 h (Martín-Vide and Llasat, 2018), high precipitation rates can remain during several hours over individual catchments. This persistence is often associated with prominent orography or quasi-stationary convergence lines that anchor convection (Kolios and Feidas, 2010; Amengual et al., 2015).

In the Spanish Mediterranean region, many small- to medium-sized catchments are steep and highly urbanized, and flood-prone areas are densely occupied. Many of these rivers are ephemeral, with short hydrological response times, and they are dominated by extreme events of low frequency and high magnitude. All these hydrological characteristics make flash flood forecasting and warning a huge challenge for flood risk management (Marchi et al., 2010) and, more specifically, create challenges for flood risk perception, awareness and communication strategy (i.e. Bodoque et al., 2019).

The present study tackles a forensic reconstruction of the catastrophic flash flood that occurred on 9 October 2018 in the ephemeral river of Ses Planes, which crosses the town of Sant Llorenç des Cardassar, located east of the island of Mallorca (Fig. 1). An extreme rainstorm triggered a large magnitude flash flood that eroded and transported woody debris and sediment from the headwaters and along the fluvial valley, killing 13 people (4 in the town of Sant Llorenç) and damaging more than 300 dwellings, 30 stores and 324 vehicles (https://sinobas.aemet.es/index.php?pag=detail&rep=1221, last access: 25 June 2019). The total damage cost of the event was estimated at EUR 91 million (Govern de les Illes Balears, 2018).

The methodology used for the reconstruction of the event was organized on three main stages: (i) 10 min precipitation has been derived from radar reflectivity observations; (ii) two distinct fully distributed hydrological models have been implemented to accurately simulate the discharge hydrograph; and (iii) a hydraulic simulation has been performed to map the affected areas, including flooding extent and timing, water depth and flow velocity. Some of the geomorphological impacts on the main channel have been also assessed by using very high resolution orthophotographs and digital elevation models for comparison of pre- and post-flooding conditions.

This deadly flash flood had an important social impact on the Balearic Islands and in the entire country (the urban flooded area was already included in the Spanish national flood risk maps portal). The operative mesoscale meteorological model by the Spanish meteorological agency (AEMET) failed at reproducing the convective clusters which triggered the intense rainfall episode over the area. Consequently, AEMET shifted from orange to red alert for intense rainfall only when the flood peak was nearly upon the town. This extreme flood event has shaken the foundations of flood risk perception for the people of the Balearic Islands. How to face this challenge for hydro-meteorological modellers and forecasters, civil protection managers and policy makers is discussed in this paper.

2 Case study

2.1 Catchment description

The Ses Planes torrent is a small ephemeral stream located on the eastern part of the island of Mallorca (Fig. 1). The catchment has a drainage area of 23.4 km² at the entrance to the town of Sant Llorenç des Cardassar (8405 inhabitants). It is located in the Llevant Ranges, a Neogene horst structure composed mainly of carbonate deposits that have an Alpine internal compressional structure (Sabat et al., 1988). The topographic relief and the steepness of the slopes are important (watershed average slope of 18 %); over a few kilometres, the elevation increases from less than 100 m to small mountains close to 500 m. The catchment has a well-developed drainage network, with a circular (fan) shape on the headwaters and an elongated bottleneck shape before the entrance of the town (Fig. 1). Forested areas are reduced and vegetation density is generally low, due to the prominence of sclerophyllous vegetation and rainfed crops, conditioned by thin soils. The Ses Planes catchment exhibits fast hydrological responses to heavy precipitation, resulting in fast Hortonian flows during intense rainfall episodes (Estrany et al., 2010). However, high infiltration rates are also present because of the persistence of low soil moisture content and the existence of underlying karstic and dolomitic fractured bedrock that promotes deep percolation. Therefore, this catchment features a highly nonlinear hydrological response to heavy precipitation and large rainfall amounts.

The Ses Planes torrent has been affected by some severe flood events over the last half century: 12 October 1973, 3 September 1982, 25 October 1985 and 6 September 1989 (Grimalt and Rodríguez-Perea, 1989). The latter was especially important; 156 mm of precipitation recorded in 2 h generated a flash flood that affected some areas of the town and led local authorities to undertake the artificial channelization of the Ses Planes torrent where it crosses the Sant Llorenç urban area.
This small Mediterranean catchment is not gauged by any local water agency. Nevertheless, the region is monitored by a Doppler C-band weather radar of the AEMET network located 60 km away from the catchment (Fig. 1). Within this region, raw precipitation is recorded by four automatic rain gauge stations with a temporal resolution of 10 min. Daily rainfall amounts are also recorded in 17 additional rain gauges, all of them located outside the Ses Planes watershed limits (Fig. 3a). All the pluviometric and thermometric weather stations belong to the AEMET observational network.
2.2 Synoptic situation

The large-scale meteorological pattern responsible for the catastrophic flash flood event was very well defined, according to the circulation systems seen at 500 hPa and at the surface on that day (Fig. 2a). The 500 hPa analysis shows a deep trough that covered the North Atlantic, with a strong gradient of geopotential height at mid-latitudes that induced a strong south-westerly flow towards western and northern Europe. The high geopotential centre located over the northern sector of continental Europe favoured this large-scale flow. In contrast, the geopotential gradient was much weaker to the south, covering part of Morocco, Algeria and the western Mediterranean.

In direct connection with the genesis of stormy weather over the Balearic Islands, a cold cut-off low of small dimensions (diameter of about 600 km) was present at the same mid-tropospheric level over the Iberian Peninsula and its Mediterranean coast. This disturbance is well marked in the synoptic map and implies a southerly flow over the western Mediterranean, especially along its eastern flank. The depression was associated with a positive vorticity anomaly to the south-southwest that was advected by the mid-level winds towards the position of the Balearics and the northeastern lands of the Iberian Peninsula. This classical synoptic pattern, when combined with a low-level moisture feeding mechanism and convective or latent instability in the atmospheric column, is known to be conducive to heavy precipitation in Mediterranean Spain (Doswell et al., 1998; Romero et al., 1999).

Surface isobars (white contours in Fig. 2a) reveal, in addition to the low-pressure centres of the North Atlantic, a powerful anticyclone over Eurasia that covered most of the Mediterranean and determined a general flow from the southeast in the western Mediterranean region. This maritime flow was most pronounced towards the Balearic Islands and the Spanish Mediterranean coast, owing to the presence of a shallow and weak depression extending from the southern half of the Iberian Peninsula towards the Atlantic coast of Africa. The synoptic situation at 850 hPa (not shown) was very similar to the surface circulation, displaying a marked warm air advection from the southeast towards the Balearic Islands. This thermal advection is confirmed by the presence of veering winds between low tropospheric levels and 500 hPa. The humidity records taken at the main meteorolog-
Figure 3. (a) Spatial distribution of the 24 h estimated cumulative precipitation for the 9 October 2018 flash flood. Automatic rain gauges used for bias correction are shown as squares. Circles depict the daily pluviometric stations. (b) Scatter plot of the 24 h accumulated precipitation derived from radar estimates and pluviometric stations. (c) Comparison of the curves of exceedance areas for different rainfall thresholds derived from the 24 h accumulated pluviometric and radar-based rainfall amounts. All pluviometers shown in (a) have been used for the computation (21 stations). (d) Radar-driven precipitation for the 9 October 2018 episode at the Ses Planes catchment.

Figure 2b shows the IR satellite image at 17:00 UTC (19:00 LT – local time, hereafter LT), that is, at the time the torrential rainfall was occurring over the study area (see Figs. 3 and 4). Note that LT corresponds to UTC plus 2 h. This image clearly shows the cloud structure associated with the upper-level cold low, a plume extending from North Africa along the western Mediterranean with embedded intense convective nuclei. Several convective cores stand out with very cold tops to the south and above the Balearic Islands, illustrating the powerful character and high depth of the convective cells. During previous hours (images not shown), several convective clusters could already be identified to the south of the Balearic archipelago. These systems then moved northwards, affecting the north of Mallorca and west of Menorca during the afternoon and evening hours. Figure 4 shows how the precipitation evolved in response over the affected area, following a southwest to northeast direction. These extreme accumulations from a sequence of mature storms repeatedly affected the northeast of Mallorca.

The fact that the convective systems formed east of the small cut-off low identified at 500 hPa (see Fig. 2a and b) is consistent with the dynamical influence attributed to these isolated cold disturbances: the eastern flank is the zone with the most favoured upward motion across a deep column and, therefore, the preferential area for an organized and intense
release of convective instability. Since these convective nuclei developed over the sea, the trigger mechanisms most likely consisted of some sort of low-level convergence line defined by mesoscale factors ahead of the above-mentioned southeasterly current.

3 Methods

3.1 Atmospheric modelling and convective precipitation predictability

An initial numerical exploratory study was performed after it was ascertained that no operational system forecasted precipitation rates over eastern Mallorca anywhere near the recorded rainfall rates in their operational cycles (Fig. 2c and d). In particular, the operational deterministic European Centre for Medium-Range Weather Forecasts (ECMWF) model barely produced 20 mm of accumulated precipitation over northeast Mallorca during the afternoon of 9 October, for any forecast cycle. Regarding the operational HARMONIE-AROME model at AEMET, even a more severe underestimation of the amounts was forecasted over the area of interest. These models operate with grid resolutions of a few kilometres. We explored the potential of sub-kilometre resolutions using the Weather Research and Forecasting (WRF) Model, version 3.9. Specifically, a mesoscale (900 m) and a microscale (100 m) resolution simulations were performed, centred over the Balearic Islands and the Ses Planes basin, respectively, steered by possible hydrological and hydraulic modelling requirements. These numerical simulations are initialized with the ECMWF operational products. The WRF configuration is a standard suite of parameterizations used by Amengual et al. (2017) and also described at https://meteo.uib.es/wrf (last access: 12 May 2019). To account for uncertainties in initial conditions of the simulations, and to examine the potential guidance that dynamical downscaling of the 50 members of the ECMWF EPS could provide for this case, the WRF runs...
were nested in the operational cycle at 00:00 UTC on 9 October.

3.2 Precipitation analysis

The Doppler C-band weather radar located close to the city of Palma performs volume scans with spatial and temporal resolutions of 1 km and 10 min, respectively (Fig. 1). On 9 October 2018, quantitative rainfall estimations have been derived from the raw radar volumetric reflectivity scans at 0.5 and 1.5° elevations. Radar blockage has been amended by performing numerical simulations of radar beam propagation over a digital terrain model of the radar domain. These simulations aim at computing the fraction of the pulse volume blocked by the regional orography (Pellarin et al., 2002). Next, reflectivities from the two lowest radar elevation scans have been considered, depending on the percentage of blocked beam at each level. Reflectivity has been converted to rainfall rate by using the WSR-88D convective relationship (Hunter, 1996). Finally, the hourly radar-based rainfall accumulations have been compared against hourly observations from the automatic pluviometric stations of the AEMET. Biases in radar estimates have been corrected by applying a dynamical adjustment against rain gauge accumulations (Cole and Moore, 2008).

Once errors in the hourly radar-derived rainfall estimates have been amended, the 24 h cumulative amounts have been verified against the daily precipitation accumulations recorded at all the pluviometric stations. In addition, exceedance areas for the total cumulative precipitation according to the rain gauge and radar observational devices have been compared. Exceedance areas have been computed just over the land mass (i.e. excluding the Mediterranean Sea) of the spatial domain in Fig. 3a. This inland region has a whole extension of 618.0 km² and a pluviometric rain gauge density of 0.034 gauges km⁻² (i.e. one pluviometric station per 29.4 km²). The spatial distribution of the cumulative precipitation observed by the rain gauge network has been obtained after applying kriging with a linear model for the semivariogram fit. While the weather radar delineates heavy rainfall areas close to 10 km², the pluviometric network captures regions 1 order of magnitude larger (~100 km²). Therefore, the actual rain gauge network observed exceedance areas impacted by heavy precipitation up to 200 mm, while radar estimates render amounts up to 350 mm for the 9 October 2018 episode (Fig. 3c).

3.3 Hydrological modelling

The fully spatially distributed Flash-flood Event-based Spatially distributed rainfall-runoff Transformation (FEST) and Kinematic Local Excess Model (KLEM) hydrological models have been implemented to study the Ses Planes hydrological response to the 9 October 2018 flash flood. As FEST and KLEM account for a varying complexity in the description of the physical processes and model structure, a better quantification of the associated uncertainties is expected when simulating the peak discharges and flow velocities for this extreme event. In addition, possible model dependencies of the results can be detected. FEST is a continuous physically based model that accounts for the following processes: infiltration, surface runoff, evapotranspiration, subsurface flow and flow routing (Ravazzani et al., 2016). The hydrological model roots in computing the soil moisture fluxes by solving the water balance equation at each grid point (i, j):

$$\frac{\partial S_{ij}}{\partial t} = \frac{1}{Z_{ij}} \left( P_{ij} - R_{ij} - D_{ij} - ET_{ij} \right),$$

where θ is the soil moisture, P is the precipitation rate, R and D are the runoff and drainage fluxes, ET is the evapotranspiration rate and Z is the soil depth. Runoff is calculated according to a modified Soil Conservation Service curve number (SCS-CN; USDA, 1986) method extended for continuous simulation. That is, the maximum potential retention S is updated at the beginning of a storm as a linear function of the degree of saturation (ε):

$$S = S_1(1 - \varepsilon) + S_3 \varepsilon,$$

where S₁ and S₃ are the values of S when soil is dry and wet (i.e. antecedent moisture conditions I and III, respectively). The actual evapotranspiration is calculated as a fraction of the potential rate tuned by the beta function that, in turn, depends on soil moisture content (Montaldo et al., 2003). Potential evapotranspiration is computed according to a modified version of the Hargreaves–Samani equation (Ravazzani et al., 2012). Note that as the actual evapotranspiration does not play any significant role in water abstractions during flash flooding, ET is just computed at a daily scale so as to close the water balance equation. The surface and subsurface flow routing is based on the Muskingum-Cunge method (Chow et al., 1988).

As the initial antecedent moisture conditions are set up to normal in the SCS-CN method, a warm-up period has been performed to achieve an accurate estimation of the initial soil moisture content. To this end, FEST has been forced by using hourly rainfall and daily temperature data over the Ses Planes catchment from 1 August to 9 October 2018 at 00:00 UTC. During this warm-up period, the state variables evolved from the standard initial values to their appropriate values according to meteorological conditions and parameter values.

KLEM is a simple event-based kinematic hydrological model that accounts for the topographic, soil and vegetation properties. Runoff-generating processes are modelled via the SCS-CN approach, while runoff routing is simulated based on a description of the drainage system response (Da Ros and Borga, 1997; Giannoni et al., 2003). That is, runoff propagation relies on the identification of the drainage paths, which includes the characterization of the hillslope and channel networks through a threshold area procedure for basin channel-
The initial abstraction ratio ($\lambda$) was used for hydraulic modelling and flood mapping, a software that allows 1-D steady and unsteady flow hydraulics calculations (US Army Corps of Engineers, 2016). In this study, HEC-RAS unsteady flow analysis was implemented to obtain flooding water extent and timing, water maximum depth and water maximum velocity during the event. One-dimensional hydraulic models replicate water movement by solving equations formulated by applying the laws of physics. More specifically, HEC-RAS solves equations derived by ensuring mass conservation (Eq. 3) and momentum conservation (Eq. 4) between two cross sections $\Delta x$ apart, which yields the one-dimensional Saint-Venant equations:

$$\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = 0,$$

$$\frac{1}{A} \frac{\partial Q}{\partial x} + \frac{1}{A} \frac{\partial (Qv/A)}{\partial x} + \frac{g}{A} \frac{\partial h}{\partial x} = g \frac{\partial (S_0 - S_I)}{\partial x} = 0,$$

where $Q$ is flow discharge ($Q = uA$, where $u$ is cross-sectional average velocity and $A$ is flow cross-section area), $t$ represents time, $h$ is water depth, $g$ is gravitational acceleration, $S_I$ is frictional slope and $S_0$ is channel bed slope (US Army Corps of Engineers, 2016). Although Eqs. (5) and (6) have no analytical solution, they can be solved using numerical techniques, allowing the estimation of $Q$ and $h$ for every cross section at each time step (Teng et al., 2017).

The HEC-RAS model was chosen because, in terms of predictive analysis, it performs better than more sophisticated models (e.g. TELEMAC, LISFLOOD-FP) and has fewer data requirements (Horritt and Bates, 2002; Teng et al., 2017). HEC-RAS can also be adequately calibrated on hydrometric data and has proved to accurately predict flood extent when water surfaces are superimposed onto accurate high-resolution digital elevation models (DEMs). For these reasons, HEC-RAS has been applied worldwide for flood simulation purposes, especially in locations highly prone to suffer flash floods, including Vietnam (Nguyen et al., 2015), Malaysia (Alaghmand et al., 2012), Pakistan (Khattak et al., 2016), Turkey (Curebal et al., 2016), Greece (Papaoaimou et al., 2016), Spain (Ruiz-Villanueva et al., 2013) and the US (Knebel et al., 2005).

A lidar (Laser Imaging Detection and Ranging) derived triangulated irregular network (TIN) has been generated to extract detailed floodplain topography, so as to provide HEC-RAS with reliable topographical information to accurately reproduce the observed flood water balance when using the CN spatial distribution, while calibration of $\lambda$ copes with the specific lithological features of a watershed (Borga et al., 2007; Amengual et al., 2017).
rately delineate the cross sections needed to set up the hydraulic model. To do so, eight 2 km × 2 km sheets of lidar point clouds from the Spanish National Geographic Institute (http://centrodescargas.cnig.es/CentroDescargas/locale?request_locale=en, last access: 5 December 2018) have been obtained, covering Sant Llorenç town and its surroundings upstream, with an average point spacing of 0.82 m. A 1 m resolution DEM based on the returns of the laser beams generated by bare ground, buildings and roads was then created. However, due to the noise contained in some lidar point clouds, the delineation of cross sections and river bed elevations based on lidar-derived DEMs may favour the introduction of artefacts, which could cause the underperformance of the hydraulic model. To avoid this, a TIN model has been generated by using the detailed contours delineated at intervals of 1 m on the lidar-derived DEM, which serves to better define floodplain topography for flood simulation purposes, since TIN-derived cross sections present smoother curves (Costabile and Macchione, 2015). The HEC-RAS model has been set up using 40 cross sections distributed along the 4303 m of reach length to provide the model with information on channel width and bed elevation. The number of cross sections was limited by the meandering shape of the Ses Planes river at Sant Llorenç and the extraordinary extent of flooding in the city centre (cross sections wider than 300 m were required to cover the affected areas at some points), since cross sections could not intersect each other. For bridge modelling, two additional cross sections were defined, located immediately upstream and downstream of each of the seven bridges crossing the Ses Planes stream channel in Sant Llorenç town.

Upstream boundary conditions for the simulation were imposed by the FEST-modelled discharge hydrograph at the first cross section, and downstream boundary conditions were imposed by the frictional slope calculated empirically from the TIN-derived river bed slope between cross sections. Manning’s $n$ roughness coefficient values (Table 2) were based on CORINE land cover data from 2018 and adapted following Papaioannou et al. (2018). Detailed topographic information on floodplain was set up for the analysis using the HEC-GeoRAS extension for ArcGIS®, and the topographic and geometric information was depurated using HEC-RAS software in an iterative fashion. This process included the deletion of topological errors in river banks and hydraulic incongruities at bridges, as well as the filtering of cross-section-delineating points.

For dynamic reconstruction of the flash flood (i.e. its timing and the spatial extent of flood-affected areas), HEC-RAS unsteady flow analysis was applied. The plan established for this flash flood simulation started at 17:00 LT and ended at 00:00 LT on 9 October, ensuring that the entire event, as pinpointed by the FEST-modelled discharge hydrograph, was encompassed within the analysis. Since a strong agreement was found between the performance of FEST and KLEM, increasing the confidence in the numerical results in terms of peak discharge and timing, only the former simulated discharge has been used to force HEC-RAS. The computation time step was set up at 10 min (same temporal resolution as the discharge hydrograph) and the output time interval was set at 1 min, although only flooding maps (1 m resolution) every 10 min are shown. Validation of the results was performed by comparing the simulated flooded area with the observed event by the Copernicus Emergency Management Service (Sentinel-1 imagery), and the modelled water depth was compared with 32 flooding marks measured in situ a few days after the event.

### 3.5 Evaluation of flash flood magnitude and geomorphological impacts

In order to contextualize the exceptionality of this flash flood and for comparison purposes, a power metric that summarizes the magnitude of the event was used. One option for quantifying the power of moving water that drives sediment transport and geomorphic change is the unit stream power (W m$^{-2}$). It is computed as

$$\omega = \frac{\gamma QS}{w},$$

where $\gamma$ is specific weight of water (N m$^{-3}$), $Q$ is discharge (m$^3$ s$^{-1}$) and $S$ is friction slope (m m$^{-1}$, here equal to the channel slope). These three components are the total stream power ($\Omega$) that is normalized by peak flow width ($w$; Bagno, 1966).

For assessment of the geomorphological effects of the event, several remote sensing techniques were used. First, two false infrared RGB (red, green and blue) composites of Planet® high-resolution (3 m pixel size) spectral imagery were visually compared, acquired hours before and the day after the event. In these image composites, the band corresponding to the short-wave infrared (SWIR) is set to the red channel. Thus, the increasing signal of the red channel (pink) in the image after the flash flood denotes a rise in the responsive signal of pixels corresponding to bare soil, rocks

### Table 2. Manning’s $n$ roughness coefficient values used for flood modelling (adapted for CORINE land cover categories; Papaioannou et al., 2018).

<table>
<thead>
<tr>
<th>Land cover</th>
<th>Manning’s $n$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Broad-leaved forest</td>
<td>0.1</td>
</tr>
<tr>
<td>Complex cultivation patterns</td>
<td>0.04</td>
</tr>
<tr>
<td>Coniferous forest</td>
<td>0.1</td>
</tr>
<tr>
<td>Discontinuous urban fabric</td>
<td>0.013</td>
</tr>
<tr>
<td>Fruit trees</td>
<td>0.08</td>
</tr>
<tr>
<td>Land principally occupied by agriculture</td>
<td>0.05</td>
</tr>
<tr>
<td>Mixed forest</td>
<td>0.1</td>
</tr>
<tr>
<td>Non-irrigated arable land</td>
<td>0.05</td>
</tr>
<tr>
<td>sclerophyllous vegetation</td>
<td>0.05</td>
</tr>
<tr>
<td>Transitional woodland-shrub</td>
<td>0.06</td>
</tr>
</tbody>
</table>
and sediment (Lillesand et al., 2015), suggesting the occurrence of strong runoff processes with associated mudflow and sediment erosion and transport. Consequently, a huge amount of debris was deposited in several new gravel and coarse-sediment bars along the Ses Planes torrent floodplain. An estimation of the sediment deposited was made using a very high resolution DEM (6 cm pixel size) and orthophotograph (3 cm pixel size) calculated using structure from motion (SfM) techniques (Schumann et al., 2019). Both corresponded to an external unmanned aerial vehicle (UAV) photogrammetric flight (Garau Ingenieros©) from November 2018.

For quantification of sediment extent, a two-step approach was used, based on the above-mentioned very high resolution imagery and elevation data. First, image spectral analysis was used to differentiate among different cover types, and an interactive supervised classification was performed, manually defining the training samples on the RGB bands of the orthophotograph (Camenen et al., 2013). Spectral-based classification performed well when classifying vegetation types and water cover, although sediment spectral responses in the RGB bands were not distinguishable enough to correctly discriminate between sediment types (not shown). To overcome this, the procedure described in Carbonneau et al. (2005) was followed, using texture as an indicator of sediment type and its spatial patterns. Orthophotograph pixels were evaluated in a grey level co-occurrence matrix (GLCM), used to quantify how many pixels of similar grey levels are neighbours. This windowing (kernal) approach generates a textural image which retains local image texture properties using contrast calculation and allows classification of pixels into different types (land covers) based on very high resolution (3 cm in this case) images. This textural image was used to accurately classify land cover into six categories (trees, shrubs, herbaceous vegetation, water, fine sediment and coarse sediment) by means of an interactive supervised classification (manually defining the training samples on the textural image). More details about GLCM calculation can be found in Carbonneau et al. (2005).

Once the extent of the sediment deposited during the event was obtained, the heights of the event-created gravel bars and deposits were estimated by subtracting the height of each pixel in the lidar-derived DEM (data acquired before the event) from those in the SfM-derived DEM (data acquired less than 1 month after the event; Figs. 8c and 9). For volume calculation, the base area (each 6 cm² pixel) was multiplied by the height of each sediment bar pixel calculated before. In this way, each (2-D) pixel has an associated (3-D) volume which corresponds to the column above it and is defined by pixel bar height (a rectangular prism in which the base is the square pixel and the side is the height value). To compute an estimation of bar sediment weight, the volume raster layer was used, based on the above-mentioned very high resolution imagery and elevation data. First, image spectral analysis was used to differentiate among different cover types, and an interactive supervised classification was performed, manually defining the training samples on the RGB bands of the orthophotograph (Camenen et al., 2013). Spectral-based classification performed well when classifying vegetation types and water cover, although sediment spectral responses in the RGB bands were not distinguishable enough to correctly discriminate between sediment types (not shown). To overcome this, the procedure described in Carbonneau et al. (2005) was followed, using texture as an indicator of sediment type and its spatial patterns. Orthophotograph pixels were evaluated in a grey level co-occurrence matrix (GLCM), used to quantify how many pixels of similar grey levels are neighbours. This windowing (kernal) approach generates a textural image which retains local image texture properties using contrast calculation and allows classification of pixels into different types (land covers) based on very high resolution (3 cm in this case) images. This textural image was used to accurately classify land cover into six categories (trees, shrubs, herbaceous vegetation, water, fine sediment and coarse sediment) by means of an interactive supervised classification (manually defining the training samples on the textural image). More details about GLCM calculation can be found in Carbonneau et al. (2005).

Once the extent of the sediment deposited during the event was obtained, the heights of the event-created gravel bars and deposits were estimated by subtracting the height of each pixel in the lidar-derived DEM (data acquired before the event) from those in the SfM-derived DEM (data acquired less than 1 month after the event; Figs. 8c and 9). For volume calculation, the base area (each 6 cm² pixel) was multiplied by the height of each sediment bar pixel calculated before. In this way, each (2-D) pixel has an associated (3-D) volume which corresponds to the column above it and is defined by pixel bar height (a rectangular prism in which the base is the square pixel and the side is the height value). To compute an estimation of bar sediment weight, the volume raster layer per rock density (2700 kg m⁻³ for limestone) and porosity of the deposit (15 %) were multiplied.

4 Results

4.1 Convective precipitation predictability

A first set of experiments consisted of nesting the WRF catchment in the deterministic high-resolution (~ 9 km horizontal) ECMWF atmospheric model using the operational cycles of the EPS at 00:00 and 12:00 UTC on 8 October (02:00 and 14:00 LT) and 00:00 UTC on 9 October. Although all three simulations show precipitation accumulations exceeding 100 mm somewhere in the region, none of them produced rainfall above 50 mm for the afternoon and evening of 9 October. This reveals the presence of forecast errors from sources other than the resolution limit (Fig. 2c and d).

The 12 h accumulated precipitation valid at 00:00 UTC on 10 October for all members showed a high diversity of possible scenarios but none of them showed enough ability to have triggered dependable warnings over the affected area. Indeed, the field of probability of 12 h accumulated precipitation above 100 mm focused attention over the western side of the domain, with only marginal probabilities over the eastern sector of Mallorca and negligible odds at the Ses Planes catchment (Fig. 2c).

4.2 Precipitation estimates

Figure 3a shows the estimated cumulative precipitation during the day of the flood event in northeast Mallorca, where the Ses Planes catchment is located. Radar-based estimates of precipitation have been compared to rain gauge observations, showing an excellent agreement: the squared correlation coefficient is slightly above 0.98 and radar-derived precipitation features a small positive bias of 2.5 mm when averaged over the 21 rain gauges (Fig. 3b). The spatial signature of the moving train of convective cells precipitating again and again over the same region is clearly visible from the distribution of cumulative radar-derived precipitation (Figs. 3a and 4). The train of convective cells followed a south-to-north direction, affecting Ses Planes basin from 13:00 to 20:00 UTC (15:00 to 22:00 LT) on 5 October 2018. As a result, an area larger than 100 km² (Fig. 3c) was affected by an intense rain of 200 mm, with increasing values towards the centre of such area, reaching peaks of 350–400 mm in the upper parts of the Ses Planes catchment, which features fan-shaped topography. This part of the catchment lies within the isohyetal line of 300 mm and, with an extension about 10 km², functioned as a funnel, gathering the precipitation and generating intense runoff processes that rapidly accumulated flow into the well-developed hydrological network. The most intense precipitation period over the catchment lasted 4 h (from approx. 16:00 to 20:00 LT, Fig. 4), which gives an average intensity of around 60 mm h⁻¹. However, peak rainfall exceeded 100 mm h⁻¹ in the moments previous to the flood event, with 140 mm falling between 18:40 and 19:40 LT.
that added up to the 130 mm that fell in the previous hours (Figs. 3d and 4).

4.3 Coupling hydrological and hydraulic modelling of the event

After calibration with in situ measurements, FEST and KLEM have simulated peak discharges around 305 m$^3$ s$^{-1}$ at the entrance of Sant Llorenç town (Table 3). According to the hydrological simulations, peak discharge occurred at 19:20 LT in the reach 2 km upstream of Sant Llorenç and between 19:30 and 19:40 LT at the entrance of the town. A high inter-model consistency has been found between the values of the different infiltration and dynamical parameters (Table 1). Overland flow velocities ranged between 0.35 and 0.40 m s$^{-1}$, while channel flow speeds varied from 3.3 to 4.1 m s$^{-1}$, highlighting the sharp hydrological response of the Ses Planes basin after torrential precipitation.

Almost 400 mm of rainfall accumulated in barely 6 h in the fan-shaped headwaters of the watershed (Figs. 3 and 4). In spite of the large amount of water lost via infiltration and deep percolation (Tables 1 and 3), a significant amount of overland flow was rapidly routed into the river network, and streamflow, which was insignificant minutes before, rapidly increased. The hydraulic simulation shows how water started flowing through Sant Llorenç town at 19:00 LT and, in barely 10–20 min, overflooded the artificial channel at several points within the sector between bridge no. 2 and bridge no. 3, reaching depth values of about 3 m (Fig. 5). The football field, located in the meander between bridges no. 2 and no. 3, was completely flooded in less than half an hour. It only took between 10 and 20 min for the flood modelled at the entrance of the town to produce the maximum extent of affected area in the city centre: water covered the entire longitudinal path of the channel across Sant Llorenç, with the most affected areas in the vicinities of the bridges and river corners. The major peak wave entered the northern sector of the town centre around 19:40 LT, completely overflowing bridge no. 3 and adjacent areas, and began to flood the town hall square (the very town centre) with around 0.50 m of water. As the peak flow wave moved southwards, the southern sector of the town centre between bridge no. 3 and bridge no. 4 was severely affected. Water depth reached almost 1.5 m in the town hall square and the surrounding blocks, which are located 150–200 m away from the main river channel. After 20:00 LT the floodwaters receded from most of the town, except for an area located between bridge no. 3 and bridge no. 4, which remained flooded until 20:30 LT, due to the backwater effect.
of bridge clogging and the wide open topography of the surrounding non-built area. According to this numerical simulation, Sant Llorenç was only flooded during barely 1 h, which gives an idea of the sudden character of this flash flood event.

### 4.4 Flood simulation and flood area mapping

The simulated water depths from the modelled discharge and detailed flood extent have been compared against the observed flooded area by the Copernicus Emergency Management Service (via Sentinel-1 radar imagery, Fig. 6). Furthermore, the modelled water depths have been compared against the observed flooding marks from on-site field measurements (Fig. 6d). The last comparison exhibits a high correlation coefficient ($R^2 = 0.91$), indicating a good performance and reliability of the hydrological and hydraulic simulations. Figure 6a shows how the simulated flooded area mostly corresponds to that estimated via satellite, except for one section located about 800 m upstream of the town entrance. This discrepancy can be explained by the flood breaking down a stone wall and inundating the lands beyond, and this was not accurately reproduced by the hydraulic simulation. Figure 6a also shows the area corresponding to theoretical floods for return periods of 10, 100 and 500 years, given by the Spanish Ministry of Agriculture, Food and Environment for this particular area (MAPAMA, 2010). The estimated flooded area by both the hydraulic simulation and the observed event by the Copernicus agency goes far beyond the floodplain for a 500-year return period, indicating the exceptional nature of this event. The detailed maps (Fig. 6b and c) show that the inundated areas near the channel, which included residential buildings, reached water depths close to 2 m. This figure entirely agrees with in situ measurements taken inside the houses of various residents. Of note is the large extension of the flooded area inside the town (up to 100 m from side to side in some areas), compared to that which occurred upstream in agricultural lands (around 60 m width), as section plots in Fig. 7 depict. The most affected areas were those located between bridges and channel corners, due to the clogging effect they exerted on water flow. The presence of several bridges also affected the dynamical behaviour of the flash flood, as is very well observed in Fig. 7, where water velocity from the simulation is depicted. Water flowed down the natural riverbed up to where bridge no. 2 is located and where the concrete artificial channel starts (it is worth noting that the artificial channel capacity is 161.5 m$^3$ s$^{-1}$, whereas a flood peak discharge around 305 m$^3$ s$^{-1}$ was estimated). That location also coincides with a 105$^\circ$ turn in the riverbed as it is canalized; therefore, the water was forced to turn and pass through a narrower section, where the roughness of the riverbed greatly decreases. The consequence of this was a vast increase in channel flow velocity from roughly 3–4 m s$^{-1}$ before the corner to 7 m s$^{-1}$ after the corner. From there, the topography opens up to a plain zone where water flows and velocity decreases. The other major increase in velocity occurred right after the second corner upstream of bridge no. 3 (Fig. 7). This bridge occupies more than half of the flooded section, thus blocking the water and increasing its velocity upstream due to flux accumulation and generation of intense backwater effects caused by bridge clogging. The same happened upstream of the other bridges (minor orange-red spots in Fig. 7) but of a smaller magnitude.

### 4.5 Flash flood magnitude and geomorphological impacts

The estimated peak discharges have a corresponding unit peak discharge slightly above 13 m$^3$ s$^{-1}$ km$^{-2}$ and a lag time of 0.5–0.8 h (Table 3). These estimations fit well with the relationship between lag time and catchment area proposed by Marchi et al. (2010) for areas < 350 km$^2$:

$$T_L = 0.08A^{0.55},$$

with a result of 0.45 h (27 min). Note that lag time has been computed as the time difference between the net rainfall and runoff centroids. The unit stream power obtained for the natural flooded section was 1110 W m$^{-2}$. The value can be considered in the upper range for this type of small catchment with steep slopes. The magnitude of the flash flood impacted the channel, changing its morphology. High-resolution satellite images before and after the event show the geomorphological impacts over a 4.4 km channel upstream of the town (Fig. 8). A volume of 14 000 m$^3$ of sediment (5671 metric tonnes) was deposited as new bars, especially on the meanders. The sediment was composed of gravel and fine material, with sporadic blocks on top of some deposits. Some areas accumulated maximum sediment depths of 1 m. The flash flood eroded sediment from the agricultural fields on the headwaters, especially on those located over softer lithology (Cretaceous marls and limestones) in the western area. The

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**Table 3.** Range of the main hydro-meteorological features estimated from the hydrological simulations for the 9 October 2018 flash flood episode at the entrance of Sant Llorenç town. Note that lag time has been computed as the time difference between the net rainfall and runoff centroids.

<table>
<thead>
<tr>
<th>Catchment</th>
<th>Area (km$^2$)</th>
<th>Total rainfall (mm)</th>
<th>Peak discharge (m$^3$ s$^{-1}$)</th>
<th>Timing (UTC)</th>
<th>Runoff volume (hm$^3$)</th>
<th>Unit peak discharge (m$^3$ s$^{-1}$)</th>
<th>Runoff ratio (–)</th>
<th>Lag time (h)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ses Planes</td>
<td>23.2</td>
<td>316.7</td>
<td>303.4–306.9</td>
<td>17:30–17:40</td>
<td>1.0–1.9</td>
<td>13.1–13.2</td>
<td>0.13–0.26</td>
<td>0.5–0.8</td>
</tr>
</tbody>
</table>
flood also eroded shrubs and numerous trees along the channel. Figure 9 shows what occurred in the largest meander on the studied reach. The concave area of the meander facilitated deposition of a large amount of transported sediment, although woody debris enhanced the aggradational process. The original main channel moved 30 m northwards after the flash flood, with a deposition of more than 1000 t of sediment in a new fluvial stream bar (Fig. 9c). Comparing Fig. 9a and b, it is possible to identify how several trees disappeared after the flood. The new bar created by the flash flood is up to 200 m long and around 65 m wide, reaching a 1 m depth at some points. This new channel created after the flash flood is a clear example of the geomorphological effects of this large magnitude event.

5 Discussion

5.1 Predictability and hydro-meteorological modelling issues

This singular case exemplifies the complex challenges faced by scientists, hydro-meteorological forecasters, civil protection managers and policy makers in predicting Mediterranean flash floods. Without a doubt, the main challenges of prediction in this instance were the small spatial and temporal scales of multiple elements, which contributed specifically to the tragic urban flash flood of 9 October 2018 at Sant Llorenç. Determinant precipitation structures at the sub-kilometric scales in the convective systems affecting the eastern Balearic Islands were identified in previous sections, severely impacting the hydrological catchment. Among conventional precipitation prediction methods, statistical techniques using historical records, such as analogues (Hamill et al., 2006), pattern-based mapping (Nuissier et al., 2011) or statistical downscaling of large-scale forecasts (Wilks, 2010), are of very limited value for the warning protocols.
over useful forecast ranges. The inability of the numerical weather prediction models to sufficiently forecast the location, intensity and timing of the precipitating systems that triggered the tragic flood on 9 October 2018 in the village of Sant Llorenç outlines important challenges and research questions for the hydro-meteorological communities. Likewise, when model errors are also considered by activating stochastic perturbed parameters in the boundary layer and land surface parameterizations in WRF (Jankov et al., 2017), the location and intensity of predicted torrential rain cells are not significantly improved (not shown). However, regarding precipitation amounts and the usable limits of these 12 to 24 h forecasts for early warnings and civil protection awareness, these exploratory ensemble prediction systems show the possibility of maximum 12 h accumulations exceeding 250 mm at distances below 30 km from the St. Llorenç catchment for this particular event. Given the aforementioned characteristics of the catchment and the fairly typical location errors of determinant convective cells obtained for this case, these state-of-the-art sub-kilometric ensemble predictions may well illustrate a serious predictability limit of precipitation structures usable in hydrological forecast systems over 12 to 24 h lead times. In this context, an ideal hydro-meteorological forecasting system suited for suburban scales should combine an accurate sub-kilometric representation of the precipitating systems, decametric resolution in the hydrological modelling, and metre or sub-metre precision in the hydraulic component of the forecasting chain. These ambitious spatial requirements are linked to, and thus also determine, the temporal scales accounted for in each modelling phase.

### 5.2 Radar-derived rainfall estimates

Despite predictive models failing to foresee and reproduce the huge amount of precipitation recorded in the northeastern part of Mallorca during 9 October 2018, we were able to accurately estimate it using radar information. However, the high spatial variability and uncertainty associated with convective storms introduces limitations when deriving...
precipitation estimates with radar at long distances (Burcea et al., 2019). Fortunately, the Doppler weather radar is located 60 km from the catchment, allowing us to obtain very accurate precipitation estimates. This is important since the region features an unevenly distributed meteorological network and, more specifically, for the studied catchment which despite several flash floods occurred over the last decades, still lacks automatic weather and gauging stations for rainfall and streamflow data recording. A comparison of the areas over which a given amount of accumulated precipitation was exceeded, according to Sant Llorenç' surrounding rain gauges and radar measurement devices, reveals that the sampling characteristics of the former network were not small enough for a correct delineation of the heavy rainfall areas (Fig. 3c). The highly local spatial scale at which heavy rainfall developed prevented its suitable observation by the relatively dense but irregularly distributed pluviometric network (Marchi et al., 2010). In this context, accurate reproducibility of precipitation amounts generated by intense convective rainfall episodes in ungauged catchments using radar data represents a significant contribution for regions with sparse or uneven distribution of meteorological stations.

The total precipitation volume during the event, with an areal basin average close to 317 mm, was 3 times larger than the monthly climatological precipitation for October, recorded in the nearby town of Artà (100 mm yr$^{-1}$), and just half of the annual climatological precipitation (696 mm yr$^{-1}$; climatic average 1974–2014). Furthermore, it clearly surpassed the daily precipitation value (210 mm d$^{-1}$) for a return period of 500 years, estimated by the local government of Mallorca island for that particular area (DGRRHH, 2001), indicating the exceptional nature of the event.

The question that remains is why such amounts of precipitation fell over that catchment and not on nearby areas. Two hypotheses may explain this phenomenon: on the one hand, the existence of a stationary convergence line that favoured convection on that particular south–north fringe; on the other hand, the anchoring effect of the orography, slowing down the movement of the convective cells train. However, the mountains of the catchment are not high enough to produce
such an anchoring effect; thus, the role of orography was limited to just enhance the convection uplift as the convective cells moved northwards.

The very accurate radar-derived precipitation estimates obtained were the main input of the hydrological models, and this represents a vital step in the reconstruction of the event. The robustness of the method used and the accuracy of the estimations increased the reliability of the subsequent hydrological and hydraulic simulations. Nevertheless, it is necessary to reduce processing time and facilitate access to near-real-time information broadcasting for meeting early warning purposes. This is operatively complex and implies investment, both in working force and in funding.

### 5.3 Hydrological modelling

Comparison in the performance of the simulated hydrographs by two distinct hydrological models has served to better quantify the associated uncertainties when simulating peak discharges and flow velocities for this extreme event. The strong inter-model output consistence highlights the basic equivalence of the numerical simulations for the 9 October 2018 extreme flash flood when considering different degrees of model complexity.

The simulated peak flows are close to the expected discharge for a 500-year return period and depict specific peak discharges slightly above $13 \text{ m}^3 \text{s}^{-1} \text{km}^{-2}$ (Table 3). The extremely sharp rising limbs denote a very fast time to peak (50 min in the case of FEST), which may be explained by several factors such as sparse and low-density vegetation, steep slopes, thin soils and watershed topography. These physical characteristics, together with the overwhelming rainfall intensity, resulted in fast Hortonian flows that favoured the rapid generation of streamflow with lag times shorter than 1 h (Table 3), increasing the hazardous component of the forthcoming flood.

Simulated unit specific peak discharges for the 9 October 2018 ($\sim 13 \text{ m}^3 \text{s}^{-1} \text{km}^{-2}$) event were similar to those

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**Figure 9.** View of the Ses Planes stream at the meander 2 km upstream of Sant Llorenç town: (a) December 2014 orthophotograph (25 cm) superimposed onto a lidar-derived DEM (1 m) before the event, and (b) November 2018 orthophotograph (3 cm) dropped onto an SfM-derived DEM (6 cm) after the flash flood. (c) Geomorphological changes and details of the sediment bar created during the flash flood at the meander.
recorded in other catastrophic flash floods that have occurred in the Mediterranean basin. Delrieu et al. (2005) indicated specific peak discharges between 10 and 30 m$^3$ s$^{-1}$ km$^{-2}$ in several watersheds of the Mediterranean Gard region in France (the so-called Gard event) during a catastrophic flash flood event that occurred on 8 and 9 September 2002. This flood was at a larger scale (in terms of rainfall amount and the extent of the affected areas) than the flood at Sant Llorenç. Furthermore, the estimated specific peak discharge for the Sant Llorenç flash flood is 1 order of magnitude larger than those recorded by Tarolli et al. (2012) in selected Mediterranean small- and medium-sized basins of Italy, France and Spain.

The modelled hydrographs for the 9 October 2018 event exhibit very steep rising limbs that fall in less than 2 h. These features are similar to other observed hydrographs of significant flash floods over Spain, such as the region of Valencia (Camarasa-Belmonte and Segura-Beltrán, 2001), the Gredos range in central Spain (Ruiz-Villanueva et al., 2014) or the lower reaches of the Guadiana basin (Ortega and Garzón-Heydt, 2009). However, in most cases, both absolute and specific discharges generated during these flood events were much lower than in the case of Sant Llorenç.

5.4 Hydraulic simulation performance

The hydraulic model has simulated a flood extent very similar to the one delineated by the Copernicus Emergency Management Service. The main differences have been an underestimation of the modelled flood extent in the reach immediately before the entrance of Sant Llorenç, due to a break in a wall, and the greater extent of the modelled flood in the north-eastern quadrant of the town centre. The latter may not be an overestimation as several Sant Llorenç locals confirmed that those areas were flooded during the event. Moreover, 32 in situ after-event flooding marks have been successfully compared with the simulated depths. Therefore, the hydraulic simulation forced with the FEST model has been very accurate in terms of flood spatial extent delineation (Papaoannou et al., 2016), serving as an additional verification check for the hydrological experiments.

The larger extent of the flooded area at Sant Llorenç compared to the reach upstream of the town can be explained by several factors: the aforementioned effect of bridges and channel corners which blocked the water and the transported sediment and debris; the topography, as the town is located in the flattest (therefore susceptible to be flooded) area; and, finally, the effect of concrete and pavement, which prevented infiltration and increased the kinematic energy of the water body and consequently the destructive power of the flash flood.

The simulated flow velocities introduce more uncertainties since the results cannot be verified by comparison with direct measurements. However, flow velocities simulated with both the hydraulic and the hydrological models are consistent with those found by Ruiz-Villanueva et al. (2014), who obtained flow velocities above 3 m s$^{-1}$ for a peak flow discharge of 120 m$^3$ s$^{-1}$ (less than half of the estimated peak discharge at the entrance of Sant Llorenç) for a catchment of 15.5 km$^2$ in central Spain. They also observed how flow velocity highly increased at bridge locations and generated intense backwater processes. Additionally, Yalcin (2019) simulated maximum velocities around 4 m s$^{-1}$ for an expected peak flow of 25 m$^3$ s$^{-1}$ in a 11 km$^2$ catchment in central Turkey. In this context, the use of the 1-D approach for the analysis of bridge effects may not properly simulate the interactions between bridges and flow, and backwater effects may be underestimated or neglected (Costabile and Macchione, 2015). This seems not to be the case for the simulation of the Sant Llorenç event since flow velocity greatly increased at all bridges. In addition, the sections between bridges no. 3 and no. 4 were flooded for a longer time, denoting that the model successfully modelled the occurrence of intense backwater processes at these locations.

5.5 Flash flood magnitude and geomorphological impacts

Estimated peak discharges, unit peak discharges and lag times give an idea of the extraordinary and sudden character of the flash flood that occurred in the Ses Planes ephemeral stream. The unit stream power of 1110 W m$^{-2}$ is related to bank erosion and deposition and to the risk of substantial channel widening or major geomorphic change (Yochum et al., 2017). This value is similar to other flash flood events which caused a major geomorphic response in an alluvial channel, reported for small streams in the Mediterranean climatic region (Marchi et al., 2016). Although the analysed stream features steep slopes and has an area similar to other studied catchments, several studies reported 1 order of magnitude more on unit stream power for the latter events (i.e. Baker and Costa, 1987; Batalla et al., 1999).

After the flood, a significant trend in channel widening was observed, similar to other stream floods (Righini et al., 2017), with a large accumulation of gravel and fine material in new fluvial bars. The accumulation of woody debris decreased transport capacity, and flow obstruction by vegetation created a positive feedback for in-stream aggradation (Merritt and Wohl, 2003; Ruiz-Villanueva et al., 2013). Along the studied reach, several trees were eroded, transported and deposited downstream, arriving at the first bridge at the entrance of the village, facilitating channel widening and erosion of the initial artificial channel, and also increasing the hazardousness of the flood peak wave, which featured a high destructive power (unit stream power > 1000 W m$^{-2}$).

Even so, it is important to clarify that the 9 October 2018 flash flood was not a hyperconcentrated debris flow. The transported sediment had a negligible impact on the peak discharges or timings. This fact is confirmed by the subsequent hydrological experiments. In situ post-event field
works have estimated a total deposited sediment volume of $1.4 \times 10^{-2} \text{ hm}^3$, while the hydrological simulations have yielded a total runoff volume ranging between 1.0 and 1.9 \text{ hm}^3 (Table 3). Therefore, sediment concentration was at most 1.4 \% of the total water volume, which is well below the concentration threshold of 6 \% from which water flood behaviour begins to be affected by sediment (Pierson, 2005).

6 Conclusion and outlook

In studying the 9 October 2018 flash flood at Sant Llorenç, it can be concluded that almost all the possible hazardous factors converged to generate this extraordinary event and its tragic consequences. Contributing factors were the inability of predictive models to foresee the convective heavy rainfall event, the synergistic effect of the storm cells’ trajectory and topography that enhanced convection in the headwaters of the catchment (insight on this matter could be provided by fine-scale numerical simulations in further research). Additional contributing factors were the very small drainage area resulting in a very short hydrological response time favoured by several ingredients, such as steep slopes, funnel-shaped watershed, low vegetation density and thin soils. These basin features favoured the acceleration of the runoff processes. Further contributing factors were the location of the town in the floodplain of the Ses Planes torrent, the artificial channelization of the stream at the entrance of the town, the presence of several bridges that acted as stoppers for flow and debris and generated intense backwater effects, a delayed red alert warning, and low awareness and conscientiousness of people. Figure 7 perfectly illustrates this last point as people crossed bridge no. 3 seconds before the water flooded the road above it. As the IPCC (2012) reported, the increase of natural risks worldwide is more related to increased vulnerability (settlements and goods located in the river floodplains), socio-economic impacts (land use changes) and perception (low awareness and preparedness) rather than to increased hazardousness. This idea is corroborated with the analysis performed in this study. This extraordinary convective rainfall event (> 300 mm d$^{-1}$ estimated versus 210 mm d$^{-1}$ expected for a 500-year return period) and the magnitude (305 m$^3$ s$^{-1}$ modelled versus 348 m$^3$ s$^{-1}$ expected for a 500-year return period) and impacts of the flood were aggravated by human-dependent factors. This relationship between intense rainfall events and increased hazardousness due to anthropogenic factors has become a dominant pattern in the Mediterranean region (Llasat et al., 2014), and it represents a major setback for effective flash flood predictability and warning.

A question remains with respect to both the maximum lead time and precision in the characterization of this flash flood, linked to the location, intensity and mode of the precipitating systems responsible for this tragic event. This case study has revealed the limited accuracy of the numerical weather prediction models when locating torrential precipitations 12 to 24 h ahead. These predictability limits point out to the need that warning systems and civil protection activation protocols can cope with forecast errors in the range of 30 to 50 km. As important as it is to focus research efforts on characterizing and reducing these errors, it is also important to consider these errors in future warning frameworks to come.

**Data availability.** The primary data used in this study (weather radar data) can be obtained under request to AEMET. The WRF configuration and description are accessible at https://meteo.uib.es/wrf (last access: 15 November 2019). The rest of the obtained results (not shown in the article) can be provided via private copy by contacting the corresponding author.

**Author contributions.** CG, JLL, EMT, VH, AA, CR and RR designed the research. AA, JLL, VH, AMF, AH, CR and RR performed the formal analysis. CG and EMT completed the field work campaign. JLL drafted the paper. JLL, AA and AMF elaborated the figures. All authors contributed to the writing, editing and revision of the paper.

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