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Supplement of

Changes in ground deformation prior to and following a large urban landslide in La Paz, Bolivia, revealed by advanced InSAR

Nicholas J. Roberts et al.

Correspondence to: Nicholas J. Roberts (nickr@sfu.ca)

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1 Landslides in La Paz

The 2011 Pampahasi landslide is one of seven historical landslides exceeding 1 Mm³ in the La Paz area. Landslides possibly similar in size to the 2011 failure happened in 1582 and 1873 in the southwest part of the La Paz valley system, but little is known of these events aside from sparse written accounts. The first landslide affected an area of 2 km² or more and buried the villages of Canoma and Ango Ango¹, which were likely located in Llojeta Valley (Fig. S1). This landslide claimed about 200 lives (Cabeza de Vaca, 1586; transcribed in Jiménez de la Espada, 1965, p. 342-351 and in Arispe, 2011). The second event involved extensive ground movement over an area of about 8 km² (Markham, 1874) and more rapid, localized movement that destroyed an area named Tembladerani (Markham, 1874) located southwest of the city centre, causing 32 deaths (Crespo, 1902). Its location may correspond to the modern area of the city called Tembladerani (Fig. S1), although Dobrovolny (1962) applies this name to a landslide deposit in Llojeta Valley. The loss of life from these two events suggests velocities exceeding several metres per second or, at the very least, a lack of prompt evacuation. Four smaller landslides happened in the twenty-first century in the Llojeta and Allpacoma valleys near the margins of the La Paz and Achocalla basins (Hermanns et al., 2012; Fig. 1B). They destroyed about 51 homes but did not claim any lives (Roberts, 2016) (Table S1). Most of these failures involved weakly lithified, fine-grained sediments of the middle part of the La Paz Formation, including large areas that had been previously mobilized by large paleolandslides.

¹ Alternative spellings in historical documents include Hanko-Hanko Hanco-Hanco, Janco-Janco, Ancoanco, Ancu-Ancu, and Ago-Ago.

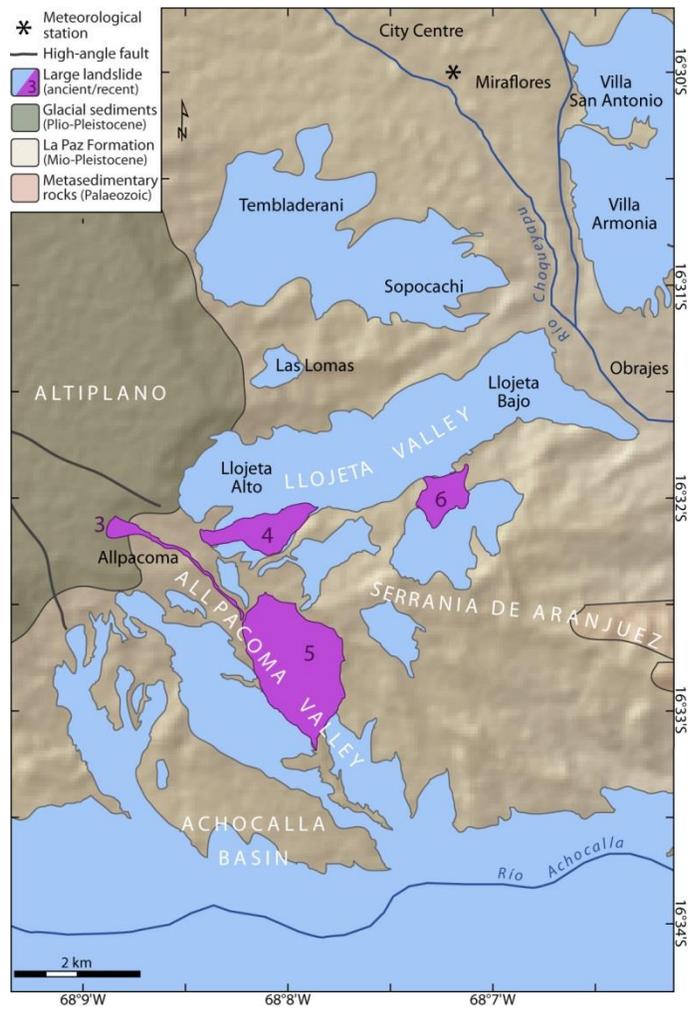


Figure S1: Locations of historic landslides exceeding 1 Mm³ in volume in the La Paz area. Landslide numbers correspond to those in Table S1. See Figure 1B for context within the La Paz area.

2 Geomechanical properties of principle units

Anzoleaga et al. (1977) provide detailed sedimentological and geotechnical characterization of lithostratigraphic units throughout the La Paz area, including units underlying the Pampahasi slope (Table S2). Their data were derived from laboratory testing supplemented by field observations of structure and lithology.

Table S2: Summary of material properties reported by Anzoleaga et al. (1977).

	Pampahasi		La Paz Formation	
	gravel	gravel	silt & sand	clay
Grain size				
>2 mm	50-75	35-75	<10	-
<80 μm	10-25	10-40	>50	-
<2 μm	<6	<12	10-40	≤ 70
Clay type*				
illite	-	-	30-70%	0-20%
montmorillonite	-	-	0-50%	70-100%
chlorite	-	-	0-30%	0-10%
kaolinite	-	-	0-20%	0-10%
CaCO₃	-	<15%	<5%	-
Iron oxide	-	'present'	-	-
Density				
Dry	1.65-2.15	-	1.75-2.10	1.20-1.30
Saturated	2.05-2.25	-	2.10-2.30	1.75-1.85
Specific	2.70-2.80	-	2.55-2.75	-
Drained strength				
Cohesion (kPa)	0 ^a	0 ^a	10-110	≥ 100
Intact shear strength	$\geq 30^\circ$	-	18-37 ^o	$\leq 14^\circ$
Residual shear strength	-	-	13-33 ^o	$\leq 8^\circ$
Atterberg limits				
Plasticity index, PI	≤ 10	-	10-25	60-80
Liquid limit, LL	≤ 26	-	25-45	90-130
Plastic limit, PL	≤ 16	-	15-20	30-50
Permiability , k	$\sim 10^{-3}$ m/s	$< 10^{-3}$ m/s	$< 10^{-5}$ m/s	10^{-5} m/s
Admissible load	≥ 3 bar	0.6-3.0 bar		

Note: '-' denotes unreported values.

3 Precipitation records

Rainfall triggers some landslides in La Paz (O'Hare and Rivas, 2005; Roberts, 2016). We thus considered precipitation records from the Laykacota meteorological station (16.5044° S, 68.1231° W, 3635 m a.s.l.; Fig. S1) located 2.5 km west of the headscarp of the 2011 Pampahasi landslide. The station has been in operation since January 1945, providing 66 years of data leading up to the 2011 failure. Data are from the website of Bolivia's Servicio Nacional de Meteorología e Hidrología (SENAMHI: <http://www.senamhi.gob.bo>). We calculated seven-day running totals to approximate cumulative precipitation and slope wetting.

As is typical at La Paz, rainfall during the second half of 2010 and first half of 2011 was concentrated during the rainy season (December-March; Fig. 4A). The 2010-2011 rainy season was slightly wetter than average, with precipitation mainly in February. February 2011 received 157.3 mm, ~70 mm more than the average for the month, and was the second wettest February on record after 1984 (170.3 mm). It was the 16th wettest month on record.

Most days during the week preceding the landslide had little or no precipitation (Fig. 4B). However, 25 February, the day before the 2011 Pampahasi landslide began, was one of the wettest (39.2 mm) in the entire 72-year period of the record and was one of only 15 days with more than 35 mm of rain (Table S3). Cumulative seven-day rainfall peaked over the next few days (26 February to 1 March) due to continued, although lesser, precipitation; this period corresponds to the four-day period of the landslide. Thus, heavy rainfall on 25 February, in combination with precipitation during the preceding days, likely played a role in triggering the failure.

Despite the high variability of short-term precipitation evident from eyewitness accounts of rainfall intensity and from daily precipitation records, the longer term (monthly to annual) amount of precipitation before and after the 2011 landslide was similar (Fig. S2). Precipitation during the 10-month, post-failure period (March to December, 2012) totalled 282.2 mm and ranged on a monthly basis from 0 to 127.6 mm. These conditions are typical of March-to-December precipitation in each of the three years fully covered by the pre-failure InSAR stack (i.e. 2008, 2009, and 2010: 0 to 137 mm monthly; 235 to 366 mm 10-month total; 282 mm 10-month mean) (Table S4).

Table S3: Times and magnitudes of the wettest 15 days recorded at the Laykacota meteorological station between 1945 and 2016.

Rank	Date	Precipitation (mm)
1	1988-01-31	53.9
2	1945-02-14	50.0
3	2009-02-08	44.7
4	2012-01-09	42.6
5	1965-02-23	42.0
6	1976-12-28	40.8
7	1981-02-04	40.0
8	2007-10-30	39.6
9	2002-02-19	39.4
10	2011-02-25	39.2
11	1980-03-05	37.7
12	1995-02-23	37.5
13	1960-01-17	37.0
14	1977-02-20	37.0
15	1947-02-02	35.5

Note: The location of the Laykacota meteorological station (16.5044° S, 68.1231° W) is shown in Figure S1.

Table S4: Comparison of rainfall (mm) during each year covered by InSAR monitoring.

	2007	2008	2009	2010	2011
March	60	67.2	53.4	31.9	52.4
April	42.9	1.1	30.5	3.9	0.8
May	4.5	4.7	0.3	20.9	8.2
June	0.1	3.4	0	0	0
July	22	2.7	15.1	2.8	10.7
August	0.1	3.1	1.5	6.2	1.7
September	52	4.8	25.7	8.3	32.8
October	49.2	23.6	27	50.2	22.5
November	35.6	12.3	75.7	9.8	25.5
December	91.5	112	137.1	109.7	127.6
Min.	0.1	1.1	0	0	0
Max.	91.5	112	137.1	109.7	127.6
Mean	35.79	23.49	36.63	24.37	28.22
10-month total (Mar. to Dec.)	357.9	234.9	366.3	243.7	282.2

Note: The location of the Laykacota meteorological station (16.5044° S, 68.1231° W) is shown in Figure S1.

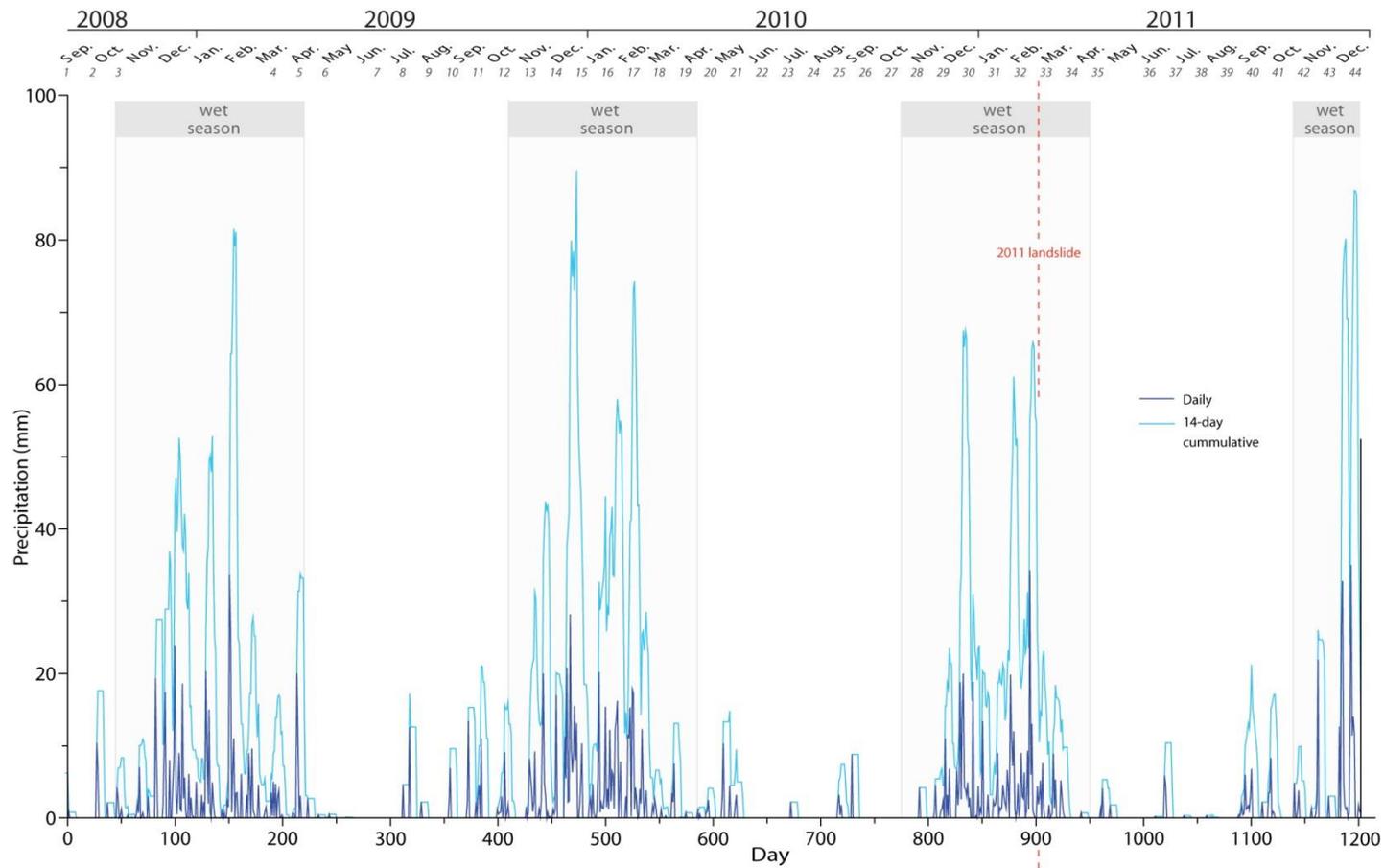


Figure S2: The precipitation record for the Laykacota meteorological station (see Fig. S1 for station location) during the full period of InSAR monitoring.

4 InSAR processing methodology

4.1 InSAR background

The ability of InSAR to measure sub-centimetre-scale ground displacements over large areas makes it a particularly useful tool for characterizing and monitoring slow-moving landslides. In recent decades, InSAR has been increasingly used in landslide investigations due to improvements of RADAR systems and processing techniques that allow for better phase recovery and increased spatial resolution.

HDS-InSAR increases the spatial density of displacement histories relative to conventional InSAR techniques through two approaches (Eppler and Rabus, 2011; Rabus et al, 2012). First, it utilizes both coherent distributed scatterers (e.g. pavement, agricultural land, and natural slopes) and persistent point scatterers (primarily built structures and fortuitously oriented rock exposures). Second, it applies adaptive filtering to preserve spatial resolution as much as possible while optimally suppressing noise from surface decorrelation. Adaptive filtering improves the spatial quality of the phase as well as RADAR echo intensity. The HDS-InSAR technique also includes several enhanced steps to remove errors introduced by other phase components, particularly the error from atmospheric water vapor variations. The HDS-InSAR processing approach generates stronger statistics for stacks of approximately 15 or more scenes.

4.2 Datasets

We applied HDS-InSAR to Fine Beam mode RADARSAT-2 scenes acquired from an ascending orbit (look direction slightly north of east) with an incidence angle of 36.3° from vertical at the image center. The dataset comprises 44 scenes collected between September 2008 and December 2011 (Table S5).

Ground resolution in the look direction of the satellite (ground-range resolution) differs across the study area due to slope angle variations in the satellite look direction and the systematic increase in the incidence angle from near range (south-southwest) to far range (north-northeast). Average ground-range resolutions for Pampahasi Plateau (horizontal in the satellite look direction) and the Pampahasi slope descending east from the plateau (11° average slope facing away from the satellite look direction) are 8.8 m and 7.1 m, respectively. Azimuth resolution across the study area is 7.7 m (Table S6).

Table S5: Scenes used in InSAR processing.

Date (yyyy-mm-dd)	Scene	Comment
2008-09-08	1	
2008-10-02	2	
2008-10-26	3	
2008-11-19		<i>Not collected</i>
2008-12-13		<i>Not collected</i>
2009-01-06		<i>Not collected</i>
2009-01-30		<i>Not collected</i>
2009-02-23		<i>Not collected</i>
2009-03-19	4	
2009-04-12	5	
2009-05-06	6	
2009-05-30		<i>Not collected</i>
2009-06-23	7	
2009-07-17	8	
2009-08-10	9	
2009-09-03	10	
2009-09-27	11	
2009-10-21	12	
2009-11-14	13	
2009-12-08	14	
2010-01-01	15	
2010-01-25	16	
2010-02-18	17	
2010-03-14	18	
2010-04-07	19	
2010-05-01	20	
2010-05-25	21	
2010-06-18	22	
2010-07-12	23	Master scene
2010-08-05	24	
2010-08-29	25	
2010-09-22	26	
2010-10-16	27	
2010-11-09	28	
2010-12-03	29	
2010-12-27	30	
2011-01-20	31	
2011-02-13	32	

Pre-failure stack

Table S5 continued....

2011-03-09	33	
2011-04-02	34	
2011-04-26	35	
2011-05-20		<i>Not collected</i>
2011-06-13	36	
2011-07-07	37	
2011-07-31	38	
2011-08-24	39	
2011-09-17	40	
2011-10-11	41	
2011-11-04	42	
2011-11-28	43	
2011-12-22	44	

Post-failure stack

Table S6: RADARSAT-2 scene details.

Incidence angle	36.3°
Slant-range pixel spacing	4.7 m
Ground-range pixel spacing	8.0 m
Azimuth pixel spacing	5.1 m
Nominal slant-range resolution	5.2 m
Ground-range resolution on Pampahasi plateau	8.8 m
Ground-range resolution on Pampahasi slope	7.1 m
Nominal azimuth resolution	7.7 m

4.3 Processing summary

The processing chain that we used is an updated version of the prototype described by Rabus et al. (2012). It includes specific steps to remove differential phase contributions due to sensor squint (Doppler) variations, incomplete knowledge of surface topography, baseline error, stratified atmosphere effects, temporal atmospheric heterogeneities, and thermal expansion, thereby isolating phase differences due to line-of-sight ground motion. All processing was conducted at MacDonald, Dettwiler and Associates (MDA) in Richmond, British Columbia, using programs developed by MDA on top of GAMMA RS modules and scripts for data ingestion and basic interferometric processing.

4.4 Pre-processing

After resampling all single-look complex images to align with a master image acquired on 12 July 2010, we produced multi-looked images (2x3 looks), which provide the highest possible resolution for roughly square ground-dimension pixels. We further produced scaled, lower resolution (8x12 looks) versions of these images suitable for atmospheric modeling.

We stitched and cropped three-arc-second Shuttle RADAR Topographic Mission V3.0 (SRTM3; Farr, 2007), reference digital terrain model (DTM) tiles to fit the scene footprint. The SRTM3 subset for the La Paz area is free of holes and other obvious abnormalities. We projected the DTM to SAR coordinates, converted elevation from a geoid to ellipsoid vertical datum, and finally calculated topographic phase for single-look and both multi-look complex phase data.

4.5 Differential InSAR

We applied differential InSAR (D-InSAR) to determine time-series phase statistics and to identify phase differences on scales greater than ~ 10 km, which are presumed to be atmospheric phase contributions. For each unique acquisition pair, we generated a two-dimensional (2D) interferogram over the entire scene area for both the intermediate (2x3) and low-resolution (8x12), multi-look dimensions. The numbers of unique interferograms were 496 and 66, respectively, for the 32-scene pre-failure stack and the 12-scene post-failure stack. Topographic phase calculated from the SRTM DTM and flat-earth phase were removed, yielding initial 2D interferograms corrected for terrain and Doppler effects. We also calculated spectral coherence for each unique image pair.

We then applied a coherence-maximization algorithm to each interferogram in wrapped-phase space to identify and correct errors in each of the four components of the interferometric baseline (parallel baseline, perpendicular baseline, and the velocities of each), as well as parameters of a static atmosphere model. The algorithm improves initial estimates of orbital parameters for each of the generated 2D interferograms.

We applied a network inversion solution and smoothing function to the coarsest multi-look interferograms to characterize large spatial-scale phase differences, presumed to result from atmospheric heterogeneities. We masked

out areas lacking coherence (e.g. water bodies) or with suspected ground motion (e.g. known landslides or areas of small spatial-scale phase fringes remaining after baseline optimization) to remove them in modeling the atmospheric phase. To reduce the likelihood of including unknown (a-priori to InSAR processing) ground deformation while also allowing adequate variation within the scene, we chose the scale of the smoothing function to be between the scale of deformation and half the scale of the scene (i.e., between ~ 3 km and 12.5 km). We removed the generated phase screens from baseline-optimized interferograms to create atmosphere-corrected interferograms.

Three main effects influence the remaining coherent phase: high-frequency topographic variability not adequately represented in the moderate-resolution DTM, cyclic movement related to thermal expansion, and permanent ground movement. Decorrelation also remains as an incoherence phase because the atmospheric screens do not contain, and thus do not remove, high-frequency noise.

4.6 Homogeneous Distributed Scatterer InSAR

We performed HDS-InSAR processing on a subset area ($\sim 3.4 \times 4.1$ km) near the center of the scene covering Pampahasi Plateau and the adjacent part of the Río Irpavi valley. As for D-InSAR processing, all steps were completed independently for the pre-failure and the post-failure stacks. Considering a spatial subset of single-look images helped facilitate timely processing throughout the remaining processing chain and limited the computational resources required.

‘Multi-looking’ – a form of spatial filtering within a weighted kernel – improves estimates of interferometric phase and image correlation (Parizzi and Bricic, 2011). HSD-InSAR employs a continuously weighted, spatially adaptive filter to group and average contiguous pixels that show similar time-series amplitude variability. The filter uses a similarity measure derived from a non-parametric statistical test (Anderson Darling) for thick scene stacks, such as the pre-failure stack, or a one-parametric statistical test (Generalized Likelihood Ratio Test assuming Rayleigh distribution) for smaller stacks (fewer than ~ 15 scenes; Rabus et al., 2012), such as the post-failure stack. The resulting neighbourhoods display spatially homogeneous spectral behaviour over time. Due to their point nature, persistent scatterers yield single-pixel neighbourhoods. Coherent distributed scatters are characterized as spatially continuous neighbourhoods, limited in extent by the dimensions of the filtering kernel applied and represented by a point at the kernel’s centre. We applied a 13×21 pixel kernel to the stacks, which restricts spatial averaging to a roughly square ground area measuring ~ 105 m on a side. The adaptive filtering improves speckle and phase while preserving sharp boundaries and point targets.

We generated 2D interferograms for the sub-set area using refined baselines and the atmospheric screen developed during full-scene multi-look processing. These interferograms included each single-look network interferogram and each multi-looked (i.e., filtered using the previously defined weighted neighbourhoods) interferogram. The later are HDS differential interferograms that provide phase change for each HDS candidate.

For every interferometric scene pair, we compared the differential phase of each pixel to a reference phase of nearby pixels just outside its neighborhood candidate window (i.e., just beyond 13 x 21 pixels for these stack). We then calculated the overall differential coherence of the pixel throughout the scene stack, which provides a measure of the quality of coherence of each HDS neighbourhood by characterizing how much a pixel varies over time from adjacent pixels outside its neighbourhood.

Solving and correcting for residual height for each HDS led to significant improvement of coherence prior to phase unwrapping and network inversion processing. As HDS-InSAR relies on prior unwrapping of the network, it contains a subsequent correction step that utilizes network redundancy to eliminate phase unwrapping errors. During this step, an initial network inversion of the unwrapped phase identifies as outliers all pixels that were incorrectly unwrapped in some of the layers of the network. Iterative removal of the outliers by the inversion process then allows calculation of their integer 2π residuals caused by the phase errors in the corresponding network layers. Phase unwrapping correction is completed by correcting the residuals for the affected pixels.

Search functions estimate the height error and linear deformation rate for each pixel of each interferogram. For each factor considered, we calculated the peak-to-peak difference – the difference between the highest and second highest maxima found during the search – for each pixel. We then combined coherence maps of the differential phase components into an overall coherence map that shows the differential phase components with the lowest peak-to-peak difference for each pixel location. This map shows the quality of the residual differential phase component at each pixel location.

We applied the aforementioned search function to atmosphere-corrected HDS interferograms, but using narrow search limits. This modeling estimates residual height corrections resulting from phase correlated with perpendicular baseline, and linear deformation rates resulting from temporally consistent phase. The former component enables correction of the reference DTM to represent true terrain. In addition to height corrections and linear deformation rates, the modeled phase includes residual phase time series.

We separated spatially coherent neighbourhoods from incoherent ones using the temporal coherence of the differential phase as a measure of quality. In separate trials, we applied multiple thresholds to the linear deformation component of the phase model; a higher threshold decreases the number of HDS candidates remaining. We determined the optimal coherence level by visually comparing incremental threshold trails and adopted the coherence value that provided the best balance between eliminating spatially variable deformation trends among HDS and preserving high-quality-phase HDS. We extracted the phase model and network interferograms for each HDS candidate above this coherence threshold.

We further flattened interferometric phase through phase demodulation. We computed the approximate deformation signal from the 2D InSAR solution of a minimum network of high-quality interferograms. The remaining linear deformation rate was calculated after removing this deformation trend from the overall phase. Phase demodulation

has two important benefits. First, it mitigates temporal wrapping due to large temporal baselines in stacks with many acquisitions over a long period. Second, it improves preservation of non-linear deformation for which the one-dimensional linear deformation fit during phase modeling performs poorly.

We further flattened the demodulated phase using the phase model for residual height, linear displacement, and thermal dilation. The resulting corrections of each HDS for topographic height error relative to the reference DTM, and temperature dilation if selected, improve coherence. We then unwrapped the flattened phase with a two-step iterative variant of the minimum-cost-function (Costantini, 1998) unwrapper, after which we added back the modeled phase components onto the HDS. We added back the deformation trend removed prior to spatial phase unwrapping onto the unwrapped HDS of each network interferogram to restore the complete deformation signal.

Using linear least squares regression, we improved the phase model by estimating residual height corrections and linear deformation coefficients remaining in the unwrapped data. Residual height errors determined by the refined phase model were removed from the unwrapped phase for each interferogram.

We inverted the network interferograms using singular value decomposition (SVD) to generate an optimum time series of interferograms referenced to a common master date. Instead of a single spatial reference point or region, phase changes in HDS-InSAR are determined relative to a cumulative reference area comprising all areas lacking movement on scales <10 km, with broader scale motion having been removed by atmospheric filtering. We smoothed the SVD-inverted time series by temporal filtering and then calculated line-of-sight displacement. The temporal filter is a least-square, low-pass filter and is optimal for irregularly sampled data, such as result from temporal gaps due to missing scenes. The filter produces weighted-average smoothing over a five-scene period spanning two scenes on both sides of each time-series position. The smoothing period is thus a minimum of 120 days for RADARSAT-2 due to its 24-day return interval.

4.7 Data output generation

We georeferenced the temporally smoothed HDS-InSAR time series for each point location using the residual height errors estimated from the phase model inversion to improve the input reference DTM. The high density of data points (e.g. Fig. 7B, C) allowed us to interpolate a linear deformation map (e.g. Fig. 7E, F) from HDS to provide a base image to efficiently represent long-term, average line-of-sight deformation over the entire area. Small HDS clusters (fewer than five points) receive no weight during interpolation, resulting in suppression of much of the localised (smaller than several metres by several metres in the case of the RADAR resolution we processed) variations that might be noise resulting from phase unwrapping errors. Finally, we exported HDS point data and the linear deformation map to a GoogleEarth-compatible plug-in (Fig. 7).

4.8 Alignment of pre-failure and post-failure displacement trends

Due to the division of scenes into two temporally discrete stacks, the magnitude of motion between the last pre-failure scene and first post-failure scene is unknown. For locations that did not experience appreciable movement during the 2011 failure event (i.e. those beyond the limits of the failure), we assume that motion between the two stacks was limited and thus used results of full-stack processing (using all 44 scenes) to align pre-failure and post-failure displacement data (Fig. 9A; ‘iv’ and ‘v’, Fig. 9B). To reduce the effect of temporal filtering, which can negatively affect data at the ends of stacks due to a lack of temporal support, we matched displacement trends from the middle portion of the partial stacks to the same trends in the full stack. For areas within the failure area, ground displacements during the failure event were on the order of metres to hundreds of metres (Fig. 2B) and thus well beyond the measurement threshold of spaceborne InSAR. For such locations the precise amount of displacement between stacks is unknown (represented by line break in Fig. 9A for ‘i’, ‘ii’ and ‘iii’).

4.9 Estimating true displacement from line-of-sight displacement

One-dimensional displacements measured in the RADAR line of sight record only one component of the true ground displacement vectors. Consequently, the line-of-sight displacements underrepresent true displacement magnitudes unless these two directions are parallel, in which case the true displacement equals the line-of-sight displacement. We estimated true displacement magnitudes by calculating the angle between the RADAR line of sight and the expected ground-movement direction to determine what proportion of the overall three-dimensional ground displacement was recorded by RADAR phase shifts. For the slopes descending east from Pampahasi Plateau, we assumed that the true deformation vector is parallel to the down-slope (fall-line) direction. The average down-slope direction of these slopes was then used to calculate the approximate true displacement rates in Figure 8A.

The displacement direction of the plateau surface behind the headscarp is uncertain. The expected declination (horizontal component) of the dilation-induced motion of the plateau surface is likely to be perpendicular to the local headscarp. However, its inclination is neither horizontal nor vertical. True displacement rates cannot, therefore, be estimated and are not suggested in Figure 8B.

5 Comparison with InSAR characterization of the 2012 Via Piave landslide, southern Italy

To our knowledge, the only other orbital InSAR analysis that characterizes landslide activity both prior to and following a slope failure is for the 2012 Via Piave landslide in southern Italy (Confuorto et al., 2017). Comparing the results of that study with those reported here highlights the unity of the HDS-InSAR technique as well as the suitability of environmental conditions at La Paz for InSAR analysis. Furthermore, the occurrence of the Pampahasi landslide between successive RADAR acquisitions allowed us to compare ground motion soon after the failure with that shortly before it. In contrast, substantial gaps (exceeding one year) in RADAR acquisitions before and after the Via Piave landslide preclude the opportunity to reliably quantify slope-activity changes immediately before and after the failure.

Confuorto et al. (2017) applied PS-InSAR and SBAS-InSAR to TerraSAR-X StripMap images covering the village of Papanice in the Crotona municipality. The scenes span two time periods separated by a three-year gap during which two landslides occurred. The pre-failure stack comprises 66 scenes acquired between April 2008 and June 2010, and was previously analysed by Confuorto et al. (2015). The two landslides happened on 23 February 2012, following two days of heavy rain. The post-failure stack comprises 34 scenes acquired between October 2013 and October 2014.

Although the RADAR scenes used by Confuorto et al. (2017) are of higher nominal resolution (3 x 3 m) than those used in our Pampahasi study (5.2 x 7.7 m, Table S6), spatial characterization of slope motion in the Italian case study was hindered by a low density of deformation records. That analysis focused on the smaller of the two 2012 Papanice landslides (Via Piave landslide; ~2 ha), seemingly in part because of a lack of usable permanent scatterers on the larger (~8 ha) landslide. The small number of reflectors identified on the Via Piave landslide in the pre-failure (~15 points) and post failure (~35 points) stacks, and their concentration in the head region limit insight into the spatial extent of activity and hinder characterization of the failure mode.

An apparent, although very slight, increase in displacement rates in the head region of the Via Piave landslide after 2012 may indicate a post-failure decrease in slope stability similar to that reported here for the 2011 Pampahasi landslide. Confuorto et al. (2017, p. 51) summarize their post-failure deformation rates as analogous to the pre-failure displacement rates (30–40 mm/a LOS) reported by Confuorto et al. (2015). They report slight increases in RADAR LOS displacement rates in the northwest sector of the landslide (part of the headscarp) from 36 mm/a well before the failure (Confuorto et al., 2017, p. 62) to 40 mm/a well after it (p. 64). The numbers of reflectors present on other parts of the landslide in both the pre-failure and post-failure InSAR scenes are small. Consequently, changes in activity in the central and lower parts of the landslide are unknown.

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